

**Development
of
Upgraded Ocean-Bottom Seismograph**

by

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Final Report

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INTRODUCTION

We have upgraded the digital electronics and recording capacity of the University of Texas Institute for Geophysics (UTIG) Ocean Bottom Seismograph (OBS) to improve its performance and usefulness in offshore seismic data acquisition programs. The new instrument is based on a CMOS computer board using an 8088 microprocessor with a C-44 standard bus structure. The system uses a UTIG-built SCSI (Small Computer System Interface) to a digital cartridge tape recorder, a Tandberg TDC-3660. We have retained the existing UTIG anchor and release, the glass sphere configuration, and the geophone sensor package. The analog front-end, A/D, CPU, memory, tape recorder interface, and tape recorder have all been upgraded. The resulting tape capacity using a standard 600XTD 1/4" tape cassette is 155 Mbytes, which is sufficient for about 30 hours of continuously recorded three-channel data at 4 msec sampling. The endurance of the system is variable, depending on the application and programming, and ranges up to 40 days.

We have successfully completed a field test of the new instruments at sea in January, 1991, through the UTIG-funded student cruise program. This report describes our development effort, which initially included both PC-based instrument and C-44-bus-based instrument, and the developed system.

TECHNICAL SUMMARY

PC-based instrument

In addition to the C-44 design we have ultimately provided, one of the design paths we pursued was a PC-architecture based on the following major components:

1. Ampro Computers, Inc. "Little Board/PC." This CMOS board with a 7.16 MHz clock provides a SCSI bus interface on the board as well as access to the PC bus directly. High-speed DMA is supported on the board, and is easily accessible for SCSI use through Ampro's extensions to the ROM BIOS (Basic Input/Output System). The boot device is an on-board PROM, from which the acquisition software would be executed. There were also provisions for the use of nonvolatile RAM, which might be used for application-variable parameters (number of channels, sample rate, shot windows, etc.) and for the storage of operational diagnostics for troubleshooting after recovery. Unfortunately, the power consumption of the board is very high, 3.4 watts as is (256 K DRAM). This aspect was regarded as undesirable, but it was not initially obvious that the C-44 design could provide sufficiently fast transfer rates to tape.
2. Real Time Devices, Inc. AD1000 A/D converter, PC bus compatible. This is a 12-bit, 8-channel analog input device with a throughput of 40 kHz. In principle, we could sample four front-end channels at 0.5 msec intervals with this board.
3. Tandberg TDC3660 streaming tape cartridge drive (common to both designs). This drive has a SCSI interface and uses the same cartridges we use in our present OBS. On a 3M DC600XTD cartridge (600 feet of tape) the TDC3660 may write up to 155 Mbytes (over 250 Mbytes on a 1000 foot tape). Tandberg has announced preliminary specifications of their 3800 series which should provide approximately 500 Mbytes of capacity on a 1000 foot tape, but these drives are not yet for sale. The streaming data transfer rate is 90 kbytes/sec, which we may maintain easily with the Little Board/PC.

The tape format is serpentine, so that we may resume writing without seeking the end of medium (the last block written). The Tandberg engineers have configured the tape such that the 12 volt supply can be turned off when the tape is idle. The logic power must remain on, consuming 1.25 watts continuously.

Work on this design option proceeded until we found a means of achieving the required 90 kbyte/sec transfer rates to tape with the slower but lower power C-44 system.

The PC design has the following advantages:

1. The necessary tape transfer rates are effortlessly achieved.
2. The high speed of the A/D converter and the CPU permitted very simple programming (no interrupts) to achieve 4-channel gain-ranged acquisition at rates faster than 1 msec sampling.
3. The A/D board design provides a versatile and easily programmable set of communication and control lines for operation and monitoring of the instrument.
4. The differences in A/D analog inputs between the PC and C-44 designs require a different analog front-end set-up. In the PC design, we used an analog multiplexer between the filter outputs and the gain ranging circuitry. This design proved usable: it did not introduce significantly more noise, and it had the advantage that the gain-ranging was uniform from channel to channel. It was this work that led to the use of Linear Technology LT1079 and LT1078 low-power, low-noise op-amps in the design of both front-ends.

The PC design has some significant defects as well:

1. The power consumption is grossly excessive. Although a design for use in short-term deployments (< 3 days) is certainly feasible, the need for some flexibility in scientific applications could not be met.
2. The design philosophy included the use of existing I/O handler software, and it was determined that the Ampro extensions to the BIOS for use with the SCSI were not installed or easily accessible before DOS (Disk Operating System) was installed. Thus, a full DOS had to be used to avoid delving too deeply into operating system development.
3. The need for the full DOS required 1 Mbit EPROMs as boot devices. The necessary chips (Intel 27C011's) turned out to have surprisingly long delivery times.

The development of this design did not proceed to full integration of the system. Our experience indicates that it is a feasible design, but it is not flexible in its application. The lower initial cost of this design might be an advantage, but it is lost after about ten or twenty deployments due to the increased battery requirements. Despite the drawbacks in operational costs and limitations, the design still seems useful, and one of us (Garmany) will seek to complete it.

C-44-bus-based instrument

Hardware Description

Figure 1 shows a block diagram of the C-44-bus-based system we developed. Some details of each new component are given below.

CPU board: — This low-power CPU board, CPU-8088 made by Onset, is based on a CMOS microprocessor 80C88 and includes a crystal-controlled real-time clock, a timer/counter and parallel and serial I/O ports. Certain modifications to the board are required, which are listed in Appendix A.

Memory board: — This board, RAM-2M made by Onset, can accommodate up to 2M bytes plus 32K bytes of static RAMs. Our developed system uses 512K +32K bytes of memory.

A/D converter board: — This 14-bit A/D board, QADC-3 made by QSI, is capable of 19 μ s conversions for 16 single-ended channels. This board became available towards the end of our development effort and replaced a slower QADC-2 board we used earlier in our system development. Required switch positions on the board are listed in Appendix A.

SCSI interface: — We designed and built this interface using a prototype board, QBOARD from QSI, because we could not wait for a commercial board being developed by QSI. A circuit diagram of the interface is given in Appendix B-a.

Preamplifier/filters: — We redesigned this front end using op-amps that consume much less power than those in our old OBS's. We also increased the number of channels to 4, including a hydrophone channel. A circuit diagram is given in Appendix B-b. The filter cutoff frequency is selectable by replacing plug-in resistor blocks. Formulae to compute proper resistor values and some selected values are given in Appendix C.

Data recorder: — We chose a cartridge tape recorder TDC-3600 made by Tandberg Data because of its low cost and adequate capacity. The current capacity is 155M bytes on a DC600XTD cartridge tape. The unit has been custom modified by the manufacturer to allow turning off the drive motor power when not in use to conserve the battery power. If appropriate, other recording devices, such as a disk drive, can easily be adapted with minimal changes in hardware.

Power relay board: — This board was designed and constructed to control the power to the recording device. Appendix B-c shows its circuit diagram.

In addition, we have redesigned the interface box that provides communication links among the OBS, a standard clock and a personal computer for the system start up, testing and clock calibration. A circuit diagram of the interface box for use with a GOES satellite clock is given in Appendix B-d, and another for use with an Omega clock is given in Appendix B-e. For a clock calibration while the OBS is at a remote location, such as on the deck awaiting deployment, a converter, given in Appendix B-f, may be used.

All the other hardware, including the release mechanism, the main chassis, the glass pressure vessel, and the anchor frame, remains unchanged from our old OBS. Figure 2 shows the prototype instrument as it exits at present.

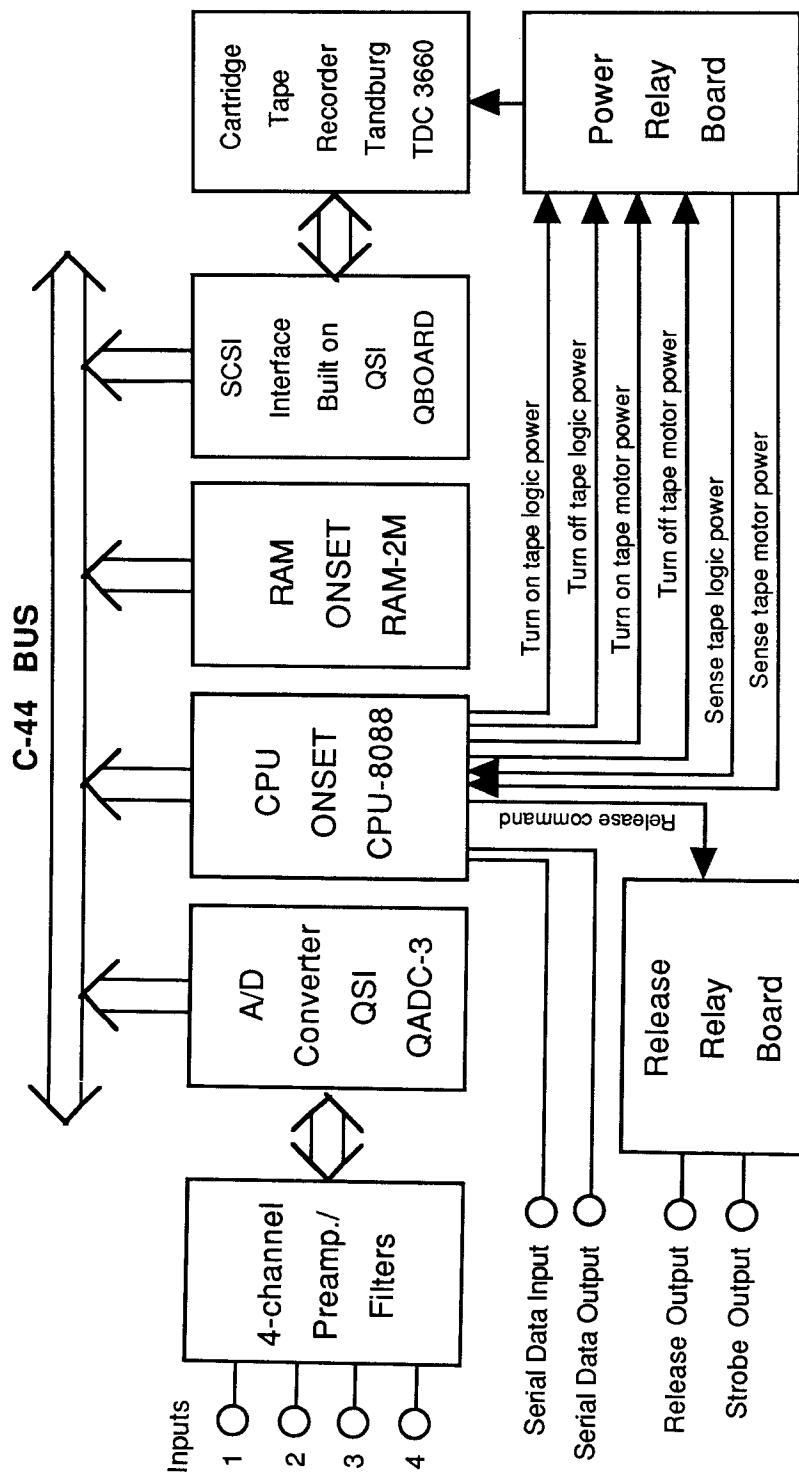


Fig. 1. Block diagram of upgraded UTIG ocean-bottom seismograph.

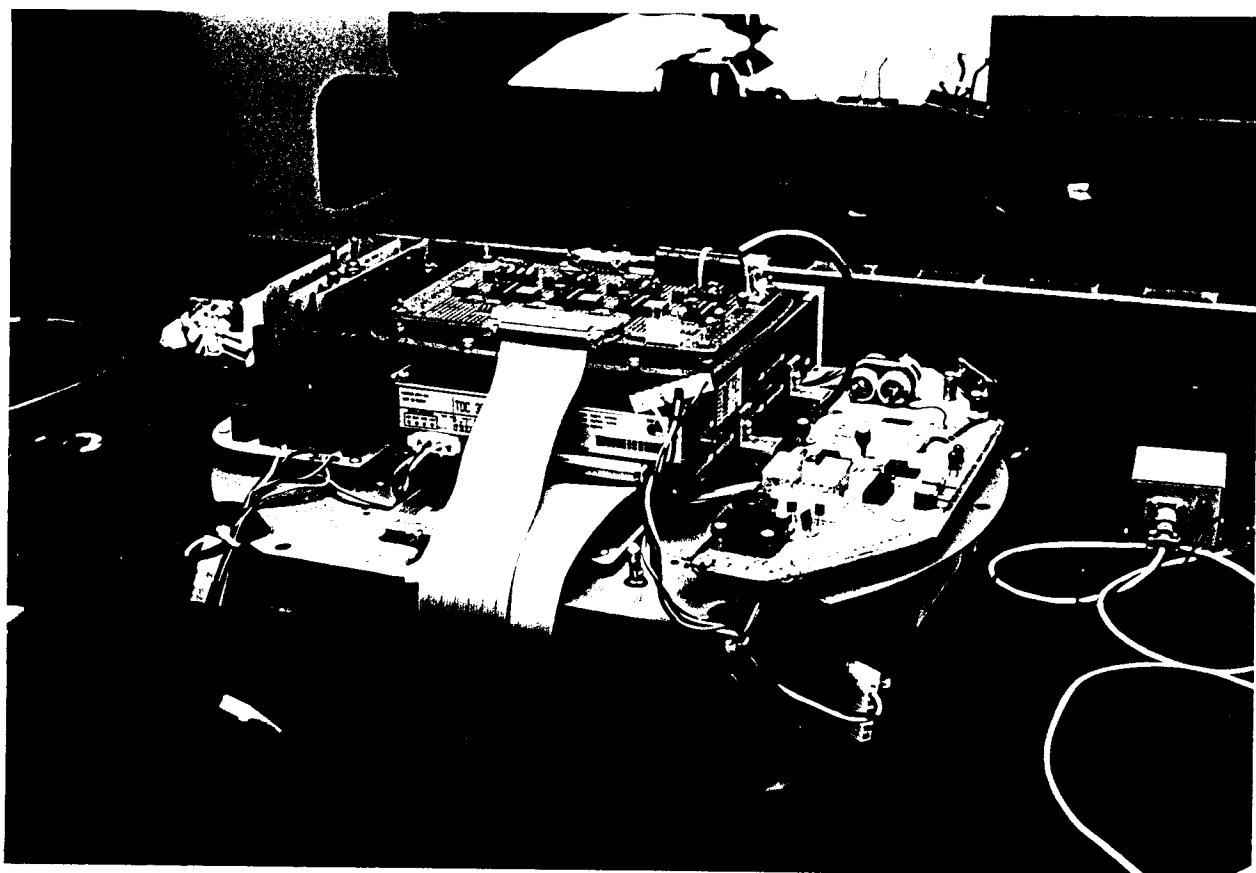


Fig. 2 UTIG ocean-bottom seismograph electronic package

A need for an accurate, common time base between the signal source (shooting ship) and the receiver (OBS), which are physically separated, necessitates a recording of the shot times at a high accuracy, generally to a millisecond, referenced to a standard clock. This, however, is not normally done on commercial shooting ships. We have, therefore, developed a shot-time trigger circuitry to record shot times to a high accuracy. Circuit diagrams of three different versions, depending on availability of equipment, are given in Appendix B-g. This "trigger box" may be used either with a logic-level input (positive or negative), often available on a shooting ship, or with an analog input, such as a towed hydrophone.

Software Description

The following is a brief description of the software to control the instrument. Appendix D gives a program listing.

1. The program starts with a UART communication through menu selections for the following actions:
 - to set the real-time clock
 - to start the real-time clock
 - to display the current time
 - to read in a shot table (recording schedule)
 - to display the shot table stored in memory
 - to activate the test mode
 - to go to sleep
 - and also to re-display the menu.
2. Once in the sleep mode, the program wakes up every minute, first to see if the release time has been reached. If it has, then the program issues a release command and goes back to sleep. If it hasn't, then the program checks to see if it is time for tape drive power up or recording start. If no action is required at the time, it goes right back to sleep. The sleep mode may be interrupted by a pressing on the push-button switch or by an activation of a magnetic switch. While in the sleep mode, the real-time clock interrupt is activated and the CPU interrupt is enabled.
3. When time for tape drive power up is reached, the system turns on the power for the tape drive motor and logic, find the end of the previously recorded data, turns off the tape drive motor power, and goes back to sleep.
4. When time for recording start is reached, the system acquires the data according to the parameters (number of channels, sampling interval and number of blocks to record) given in the shot table, turns on the tape drive motor power, records the data, turns off the drive motor power, and checks to see if the recording stop time has reached. If it has not, the system continues with data acquisition. If it has, then the system turns on the drive motor power, writes an end-of-file mark, rewind the tape, turns off both the tape drive motor and logic power, and goes back to sleep.

The sampling rate is controlled by the PIO timer counting the UART baud-rate generator output. While waiting for a sample time, the CPU stays in sleep mode with interrupt disabled. The timer wakes up the CPU through the INT-A line. While the A/D conversion is taking place, the CPU is put to sleep with the CPU interrupt disabled. Completion of each A/D conversion wakes up the CPU through the INT-B line.

The transfer of data from the memory to the tape drive takes place in pseudo DMA mode with a hand shake through the wake-up line to maintain the 90 Kbytes/s transfer rate. While recording, the CPU interrupt is enabled so that the real-time clock may issue a 30-second time-out interrupt to terminate the process if there is any problem with the data transfer and recording.

5. Upon entering the test mode, the system displays the sub-menu, which allows the following selections:

- to read the SCSI registers
- to write to a SCSI register
- to select the tape drive
- to send a command descriptor block to the tape drive
- to receive data, status and/or message from the drive
- to initialize the tape drive; i.e., to find end of data
- to output memory contents to the tape drive
- to write a file mark
- to acquire data and write to tape
- to turn on ADC power for preamplifier/filter testing
- to return to the main dialog
- and also to re-display the sub-menu.

Characteristics

The principal new features of the instrument are:

1. Simpler construction, easier operation and increased reliability, which are achieved by the use of off-the-shelf microprocessor, memory and peripheral boards
2. Greatly increased data storage capacity, with easy upgrade to still larger capacity through the use of a SCSI interface
3. Communication link through the pressure case, which allows reprogramming of the instrument for last-minute recording-schedule changes without opening the pressure case.

The instrument has the following characteristics:

Sensors:	3-component gimbaled geophones and a hydrophone; may be configured for 1-, 2-, 3- or 4-channel recording
Pass band:	4.5 - 100 Hz
Alias filters:	selectable with plug-in resistor blocks
Filter roll-off:	-24 dB/oct
Sensitivity:	1.2 nm/s with Mark Products L-15B geophones 62 µPa with Benthos AQ-12 hydrophone
Dynamic range:	126 dB theoretical, 112 dB re rms electronic noise

A/D:	14 bits plus dynamic gain ranging
Sample interval (τ):	1 to 255 ms at 1 ms steps
Number of channels (n_{ch}):	1, 2, 3 or 4
Timing accuracy:	10 ms absolute, with pre- and post-deployment clock calibrations against standard signal and water-wave arrivals
Instrument location accuracy:	10 m, from post-cruise analysis of water-wave arrival data
Instrument orientation accuracy:	1°, from post-cruise analysis of water-wave arrival data.
CPU:	80C88
Data acquisition mode:	continuous with short gaps while transferring data to tape
Temporary data memory	512 Kbytes standard, 4 Mbytes optional
Continuous record length:	261,120 τ/n_{ch} [e.g., 8m:42s @ 4 ch. 8 ms] (2,088,960 τ/n_{ch} w/ optional memory)
Transfer rate to recorder	90 Kbytes/s
Data gap:	8.1 s for 512K transfer, 47.9 s for 4M transfer
Recording capacity:	155 Mbytes
Acquisition capacity:	22.5 τ/n_{ch} hours (τ in ms)
Battery life:	40 days dormant; 28, 56 or 84 hours acquiring data (depending on battery configuration)
Power source:	24, 27 or 30 size-D lithium cells
Pressure case:	43 cm (17") diameter glass sphere
Weight at deployment:	85 kg (190 lbs)
Weight at recovery:	35 kg (75 lbs)
Overall dimension at deployment:	128 × 128 × 145 cm (50" × 50" × 57")
Maximum depth of deployment:	7 km
Method of instrument recovery:	Timed release from anchor controlled by two independent clocks

Operation

The following is a step-by-step instruction for starting up the system:

1. Prepare a recording schedule (shot table) on a Macintosh or (any personal computer). The shot table format is given in Appendix E.
2. Connect all five battery power connectors.
3. Verify all cable connections: geophones - preamp/filter; hydrophone (if used) - preamp/filter; preamp/filter - ADC board; CPU board - chassis; SCSI board - tape drive.
4. Reset the main and back-up release switches.
5. Connect the OBS to a Macintosh (or any personal computer) and a satellite clock (or Omega clock) through the communication box (com box).
6. Start Versaterm on the Macintosh [baud rate 9600].
7. Switch the com box to 'SAT' (or 'OMEGA' if Omega clock is used) and format the satellite (or Omega) clock to millisecond output.
8. Switch the com box to 'OBS.'
9. Turn on the OBS.
10. Press 'c' on the keyboard and set the OBS clock.
11. Press 's' to start the clock in synchronization with the satellite (or Omega) clock.
12. Press 't' to verify the clock.
13. Press 'r' and select 'Send Stream' from the 'File' menu to read in the shot table.
14. Press 'd' to verify the shot table.
15. Press 'm' to enter into test mode on OBS.
16. Press 'c' to turn on ADC and preamp/filter power.
17. Tap on sensors while watching signals at the preamplifier output on an oscilloscope to make sure that all sensors are working.
18. Press any key to turn off the ADC and preamp/filter power.
19. Press 'q' to exit from the test mode.
20. Press 'g' and wait till the OBS goes to sleep at the next minute update.
21. Switch the com box to 'CAL' and select 'Save Stream' from the 'File' menu to record clock calibration data.

22. Disconnect OBS from the com box.
23. Set and start the back-up release timer.

The instrument is now ready to be mounted inside a glass pressure vessel for deployment. If for any reason the clock need be reset or the shot table need be revised, reconnect the Macintosh to the OBS (step 5), switch the com box to 'OBS' (step 8) and use a push-button or the magnetic switch to wake up the system to perform necessary operations among steps 10 through 14 above. Finish the operation with steps 20 and 22.

Following recovery of the instrument, repeat steps 7, 21 and 22 to collect post-recovery clock calibration data.

The formats of the record headers and data recorded on 1/4-inch cartridge tapes are given in Appendix G.

Field test results

During UTIG Student Cruise No. 14, which took place from 8 to 13 of January 1991 in the Gulf of Mexico on board *R/V Gyre*, we deployed 4 OBS's for testing and seismic data acquisition over a salt structure. One of the instruments was the final version described in this report and the other one was the version developed earlier in the program using a slower A/D converter board, QADC-2 made by QSI, before the faster A/D converter board, QADC-3 became available. The remaining two were our old instruments upgraded with Tandberg tape drives for a larger data-storage capacity. All four instruments were programmed to acquire data simultaneously and continuously for a period of 36 hours, during which time we shot a 429-in³ (7 l) air gun every 30 seconds at distances up to about 50 km. The sampling rate was set to 8 ms for all instruments.

The two old OBS's performed as expected. Because of the limited memory capacity (72K bytes), the data on these units must be transferred to the tape drive at short intervals, consuming tape drive motor power at a very high rate. The units lasted for 19 hours and 17 hours before the tape motor power was exhausted. Both units recorded full 3-component seismic dat for these durations.

The new OBS with the faster A/D converter board recorded 4 channels of data (3-component geophone and a hydrophone) for the entire 36-hour duration of the test. A minor problem, however, was discovered: the recorded time information was occasionally late by exactly 0.3 second. It appears to have been caused by a defective real-time clock chip on the CPU board. All three seismic channels recorded excellent data, but the hydrophone channel appeared to be weak, possibly caused by a slight leakage of current at the feed-through of this high-impedance input.

Another new OBS with the slower A/D converter board may also have recorded full 36 hours of data. However, we have been unable to read past the first 2 and 3/4 hours of the recorded data because of a tape medium error in reading, suspected to be caused by a physically damaged tape. We are talking with the manufacturer of the tape drive to correct this problem. The quality of seismic signals on all channels of this 3-component unit was excellent. Sample partial seismic record sections are shown in Fig. 3.

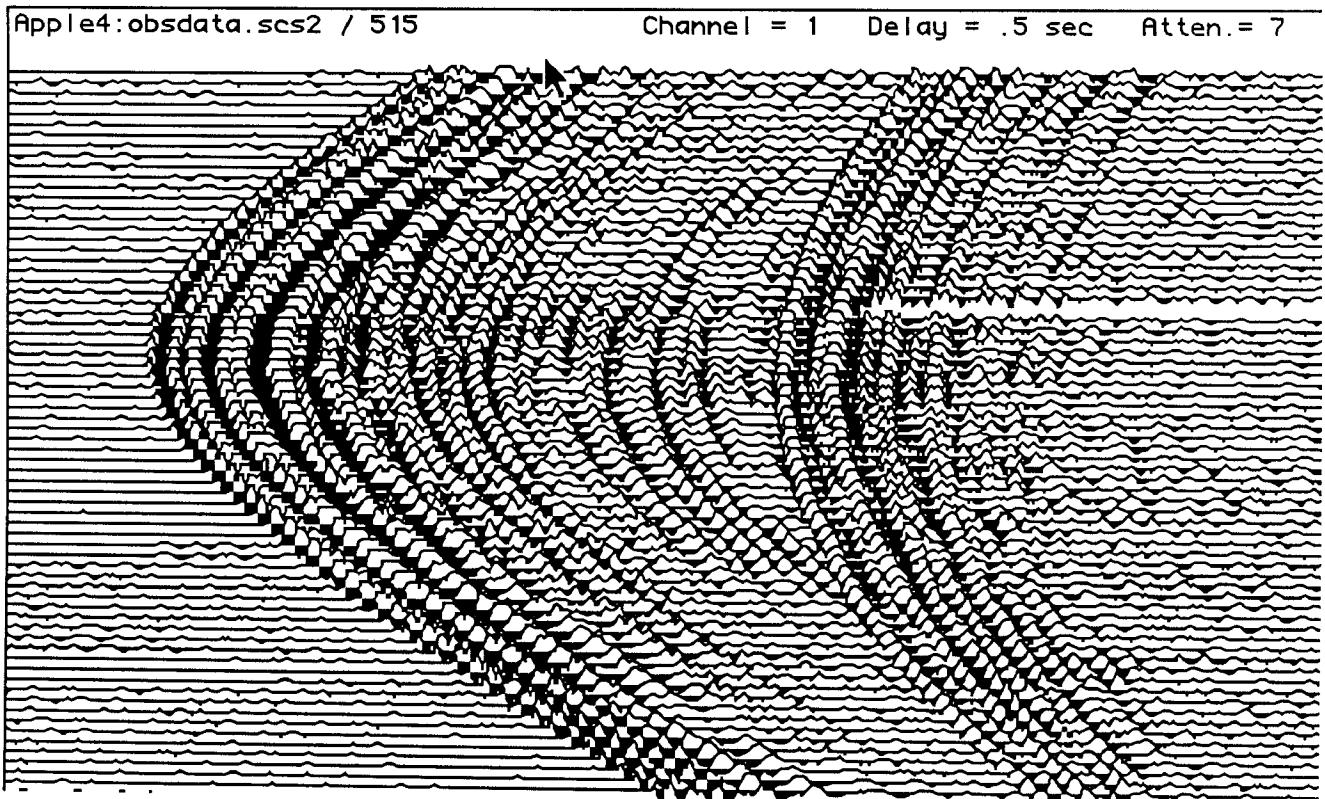
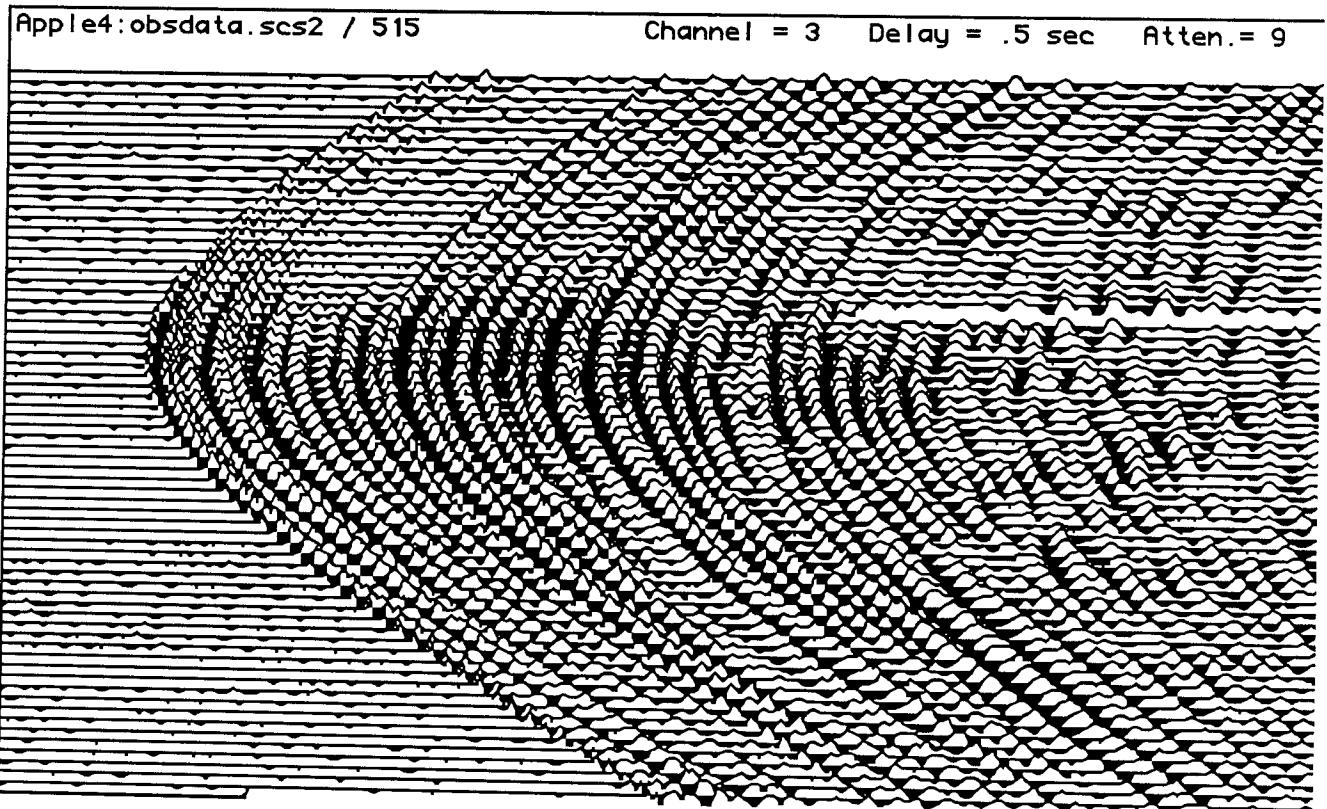
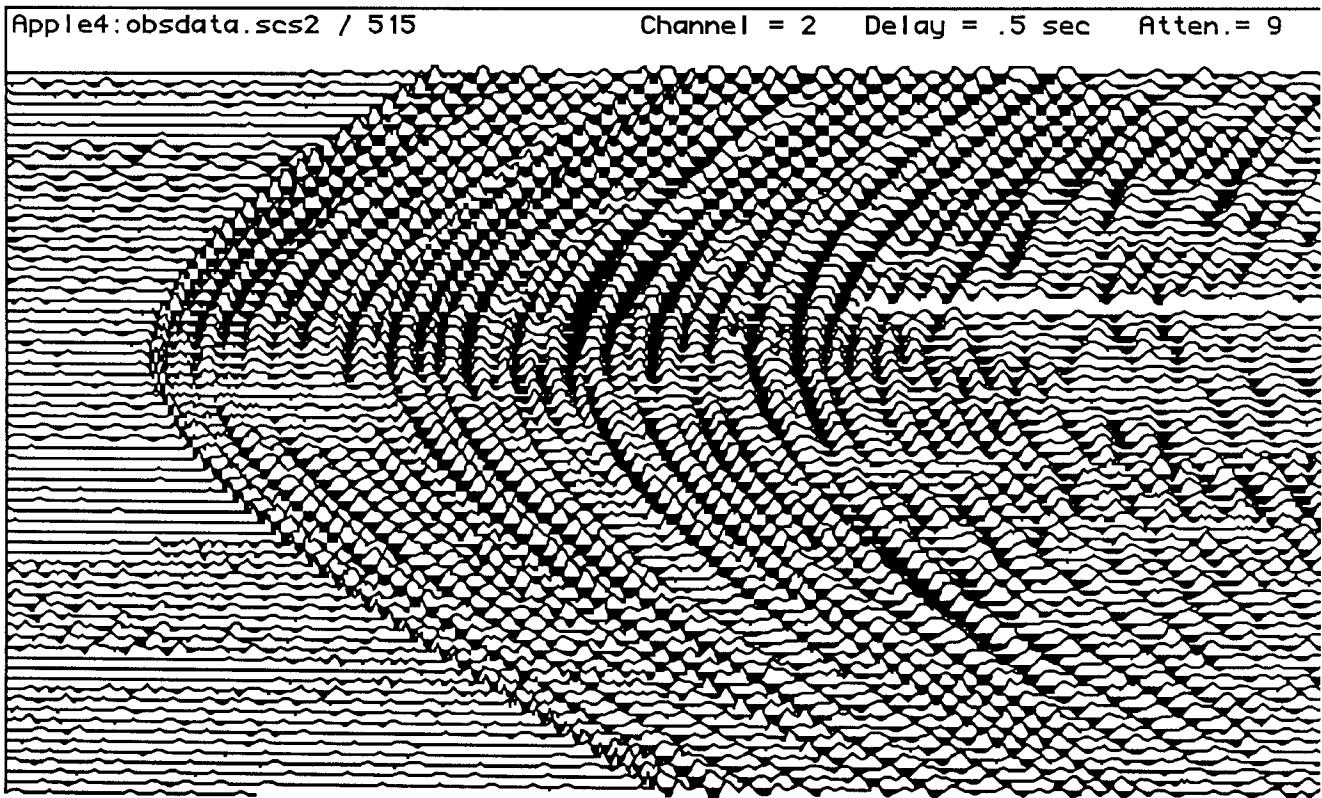


Fig. 3. Sample QC plots, on a Macintosh, of a portion of the geophone data acquired during the field test. Each trace of the record sections shows a 4.08-second section of the acquired data for each shot, which was fired every 30 seconds using a 7.0 l (429 in³) air gun. The approximate trace separation is 75 m, and thus each record section covers an offset range of about -2.0 km to +3.0 km. Channel 1 is vertical and channels 2 and 3 are two horizontal components. The missing tail of the 23rd trace was caused by a 7.7-second data gap that occurred every 11m:44s while the data stored in the memory were being transferred to the tape.



Appendix A. Required Board Modifications

CPU-8088 Board

- Connect 82C52 pin 21 (Clock Out) to 81C55 pin 3 (Timer In)
- Connect 81C55 pin 6 (Timer Out) to 74HC148 pin 4 (Int A)

QADC-3 Board

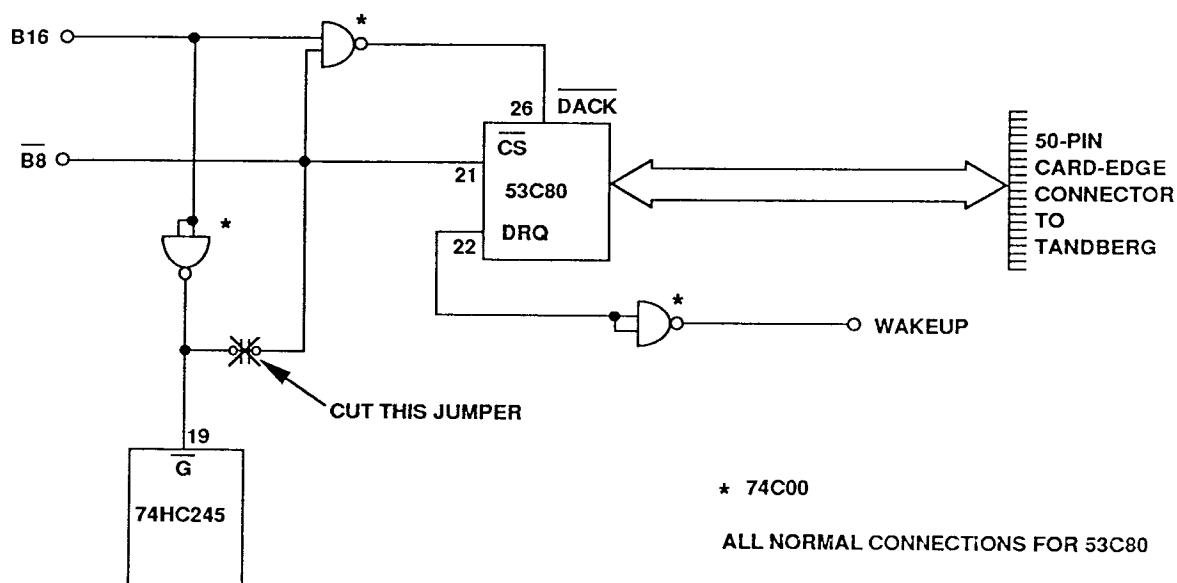
- Switch S1 - INTB on
- Switch S2 - A5 & ILV on

Appendix B. Schematic Diagrams

The following schematic diagrams follow this page:

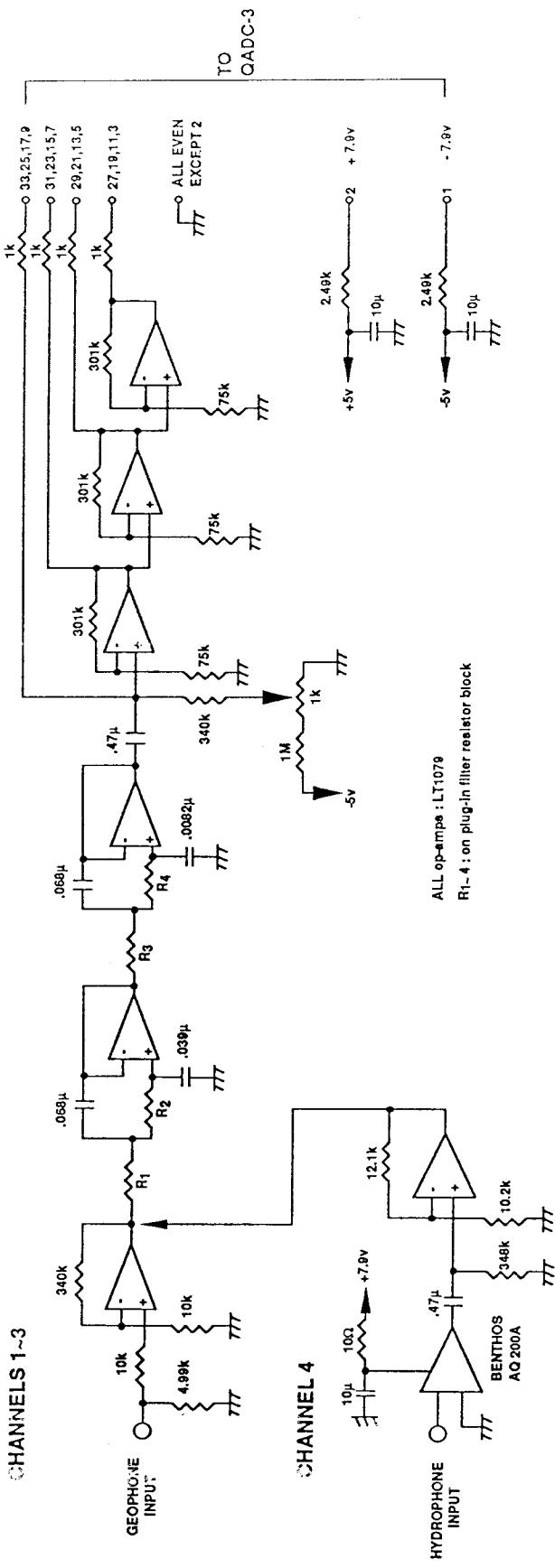
- a. SCSI interface
- b. Preamplifier/filter
- c. Tape power relay board
- d. OBS/Macintosh/satellite clock switching box
- e. OBS/Macintosh/Omega clock switching box
- f. OBS/RS-232 converter box
- g. Shot time trigger box

SCSI INTERFACE ON Q-BOARD



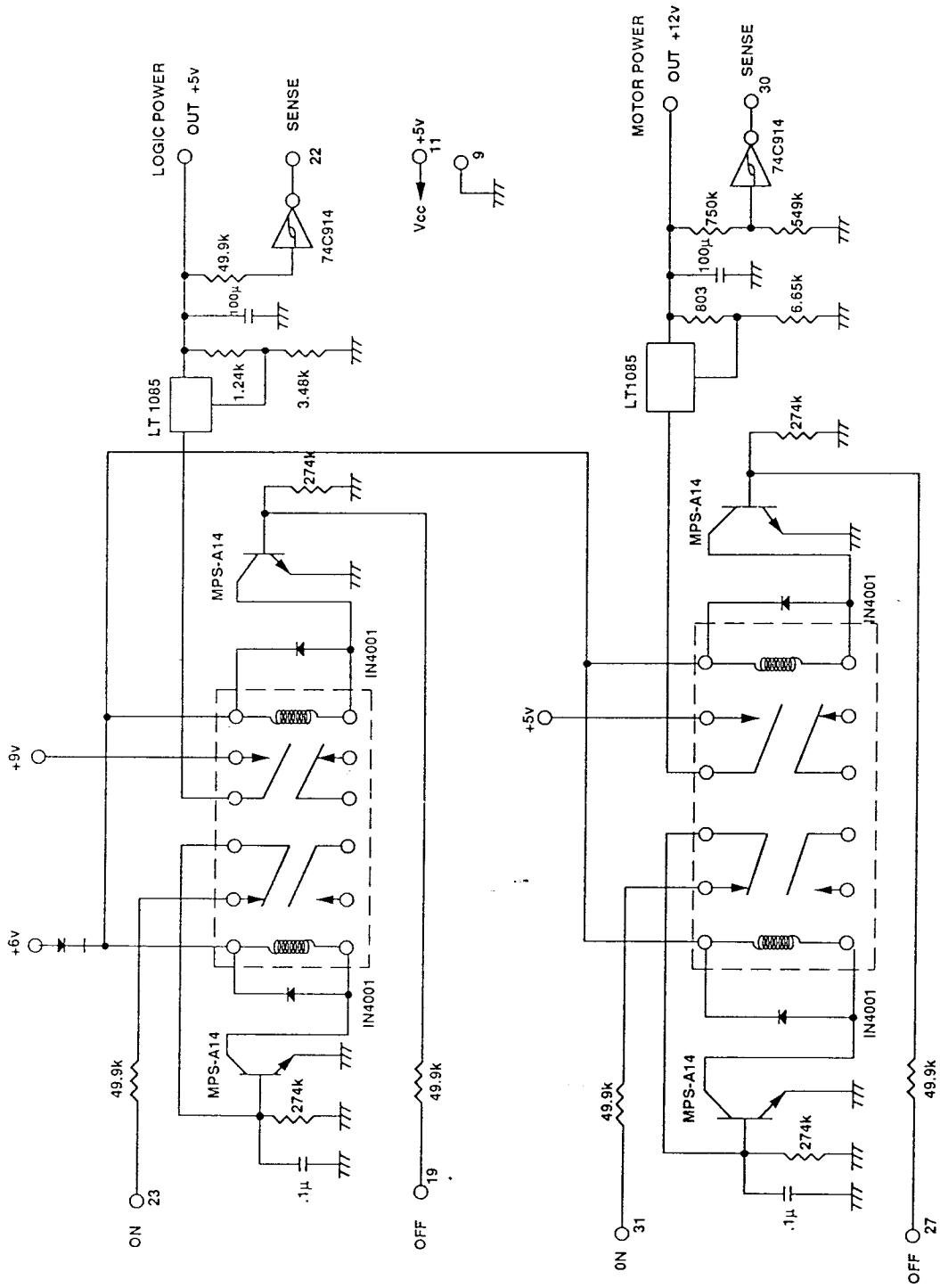
B-a. SCSI interface built on QSI Q-Board

PREAMPLIFIER/FILTER



B-b. Preamplifier/filter.

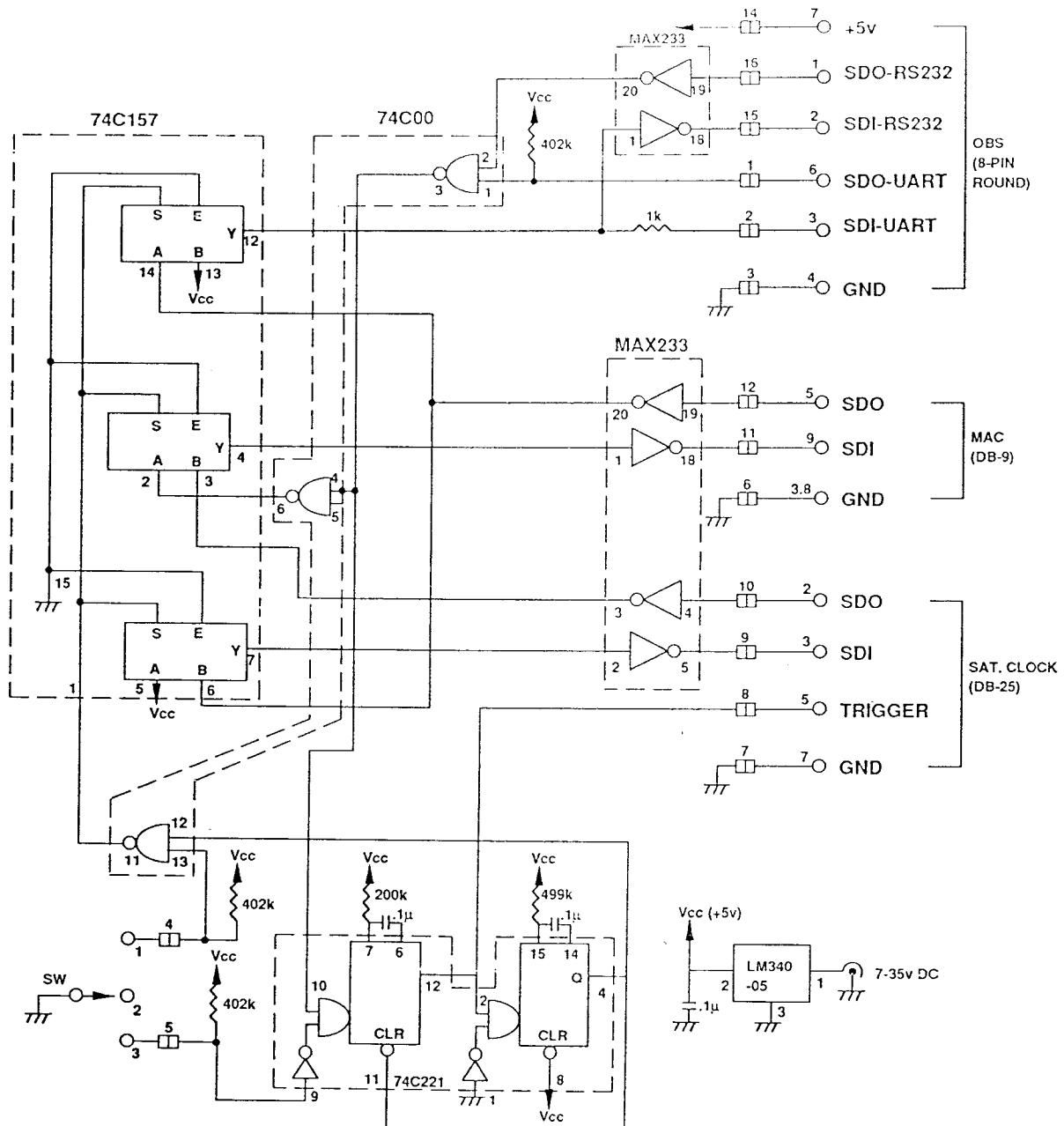
TAPE DRIVE POWER RELAYS



SMALL NUMBERS AT TERMINALS INDICATE CPU-8088 PIO PIN NUMBERS.

B-c. Tape power relay board.

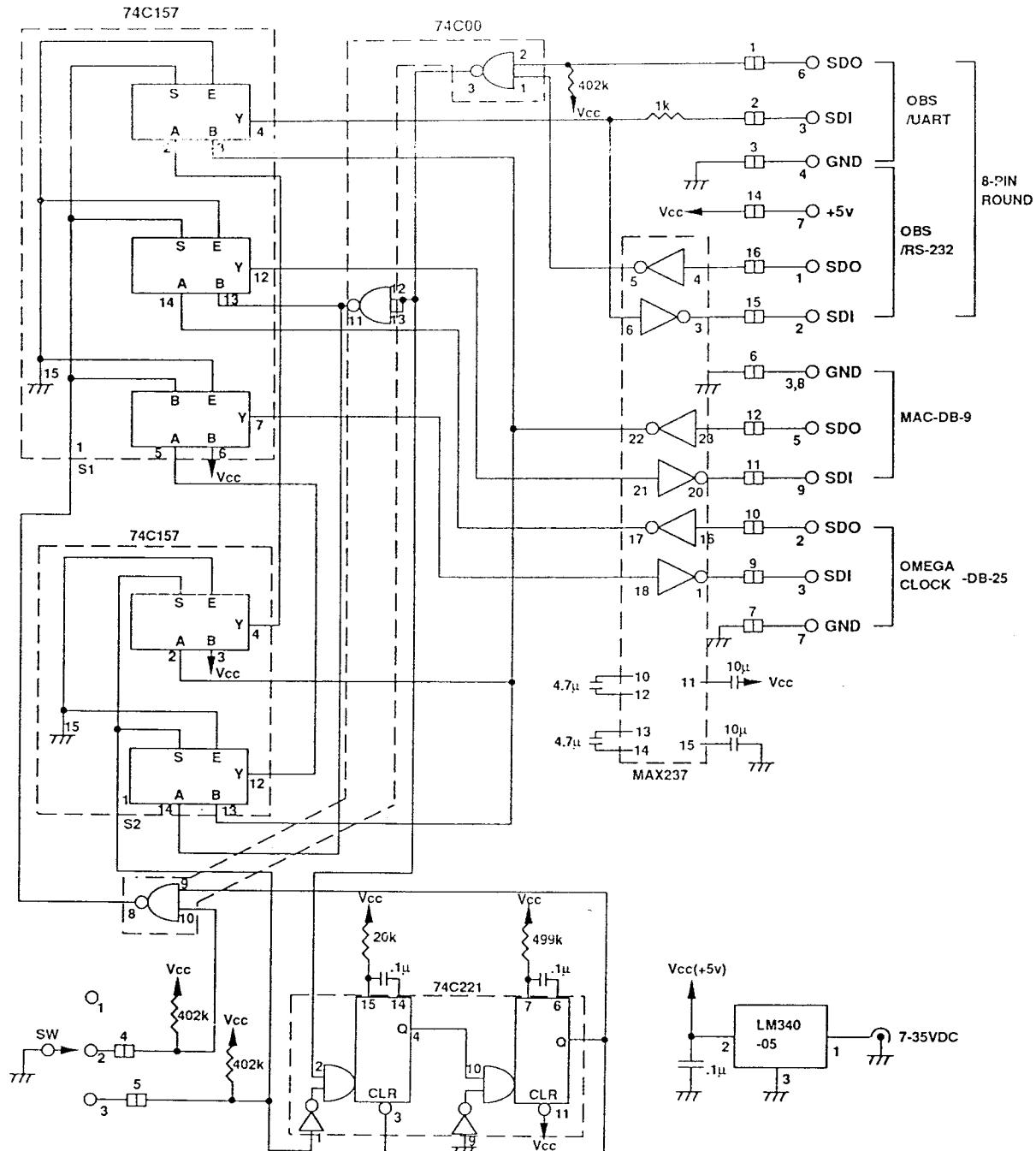
OBS/MAC/SATELLITE CLOCK SWITCH BOX



<u>SW</u>	<u>SELECT</u>	<u>TRIGGER</u>	<u>SIGNAL PATH</u>
1	B	DISABLED	SAT. CLOCK \rightleftharpoons MAC
2	A	DISABLED	OBS \rightleftharpoons MAC
3	-a	A	OBS \rightleftharpoons MAC
	-b	B	SAT. CLOCK \rightleftharpoons MAC (starts 20ms after trigger and lasts for 50ms)

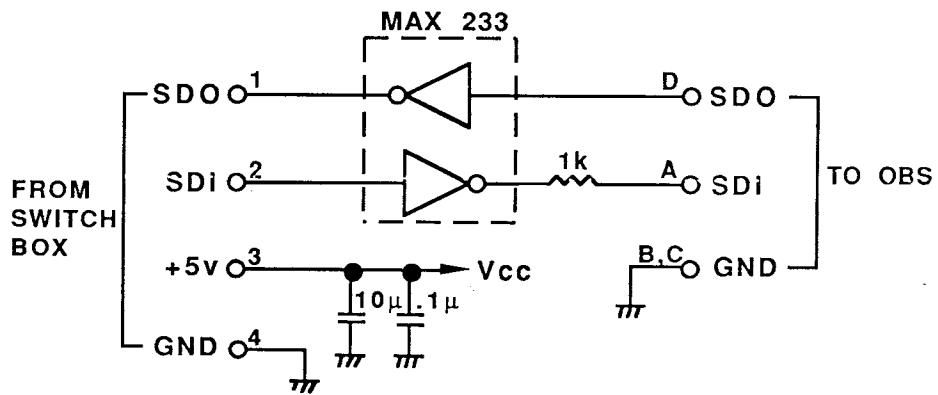
B-d. OBS/Macintosh/satellite clock switching board.

OBS / MAC / OMEGA CLOCK SWITCH BOX



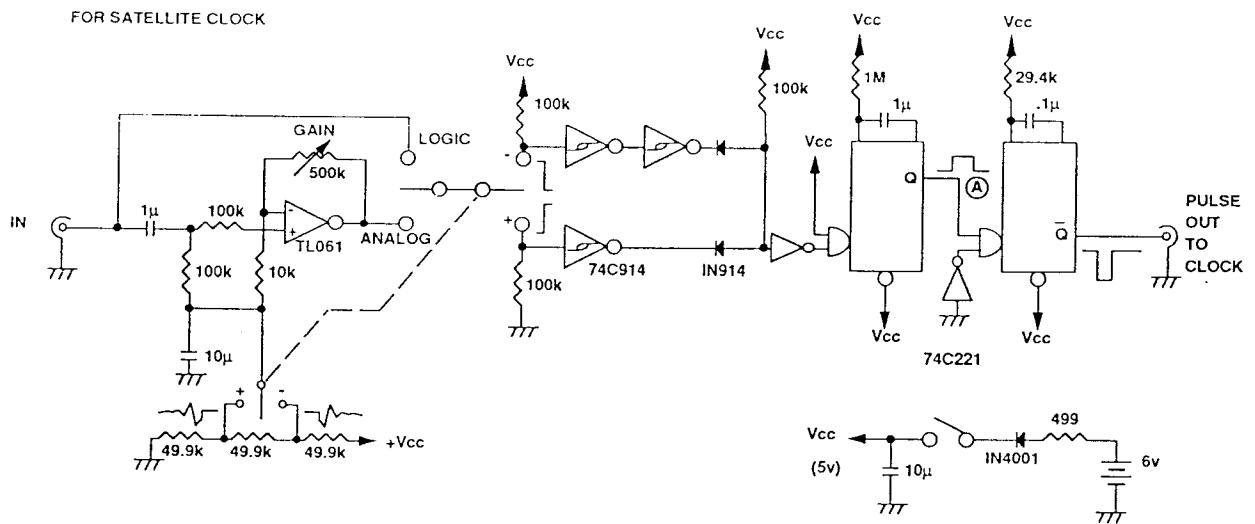
<u>SW</u>	<u>S1</u>	<u>S2</u>	<u>SIGNAL PATH</u>
1	0(A)	1-(B)	OMEGA \rightleftarrows MAC
2	1(B)	-	OBS \rightleftarrows MAC
3	0(A)	0(A)	MAC \rightarrow OBS \rightarrow OMEGA \rightarrow MAC
-b	1(B)	-	OBS \rightarrow MAC (starts 2ms after trigger and last 50ms)

B-e. OBS/Macintosh/Omega clock switching board.

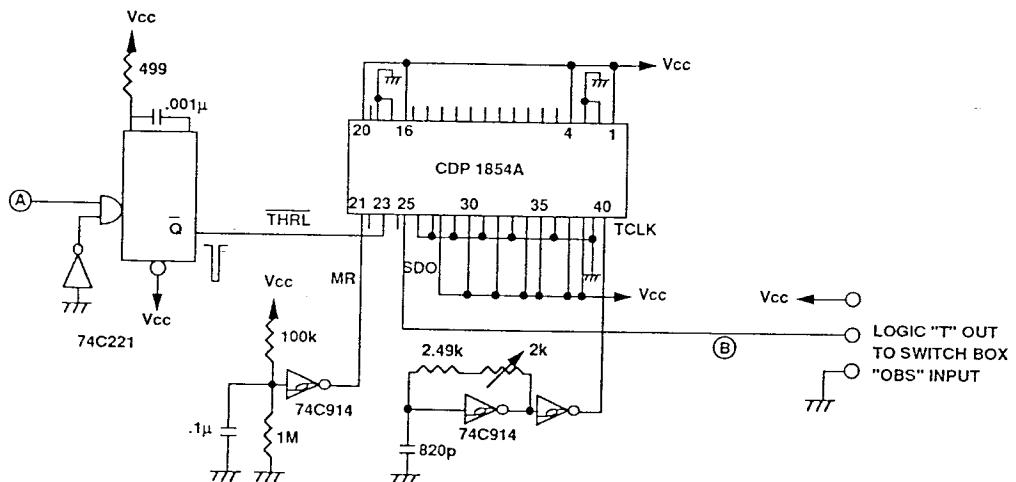
OBS / RS-232 CONVERTER BOX

B-f. OBS/RS-232 converter box.

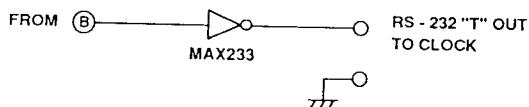
SHOT TIME TRIGGER BOX



FOR OMEGA CLOCK - COMMON SHOOTING / DEPLOYMENT SHIP



FOR OMEGA CLOCK - SEPARATE SHOOTING SHIP



B-g. Shot time trigger box.

Appendix C. Filter Resistors

Resistor values for the 4-pole Butterworth anti-aliasing filters may be computed using the following formulae:

$$R_1 = 2/[a C_1 + \{(a C_1)^2 - 4 C_1 C_2 \omega_0^2\}^{1/2}]$$

$$R_2 = 2/[a C_1 - \{(a C_1)^2 - 4 C_1 C_2 \omega_0^2\}^{1/2}]$$

$$R_3 = 2/[b C_1 + \{(b C_3)^2 - 4 C_3 C_4 \omega_0^2\}^{1/2}]$$

$$R_4 = 2/[b C_1 - \{(b C_3)^2 - 4 C_3 C_4 \omega_0^2\}^{1/2}]$$

where

$$a = (2 + 2^{1/2})^{1/2} \omega_0$$

$$b = (2 - 2^{1/2})^{1/2} \omega_0$$

$$\omega_0 = 2\pi f_0$$

$$f_0 = \text{cut-off frequency}$$

$$C_1 = 0.068 \mu F$$

$$C_2 = 0.039 \mu F$$

$$C_3 = 0.068 \mu F$$

$$C_4 = 0.0082 \mu F$$

Given below are resistor values of 1% tolerance to achieve some selected cut-off frequencies:

<u>f_0, Hz</u>	<u>$R_1, \text{k}\Omega$</u>	<u>$R_2, \text{k}\Omega$</u>	<u>$R_3, \text{k}\Omega$</u>	<u>$R_4, \text{k}\Omega$</u>
15	107	392	287	698
20	80.6	294	215	523
25	64.9	237	174	422
30	53.6	196	143	357
40	40.2	147	107	267
50	32.4	118	86.6	210
70	23.2	84.5	61.9	150
100	16.2	59.0	43.2	105

Appendix D. Program Listing

The following is a listing of program agobs2.asm, to be used with a GOES satellite clock for clock calibration, as it stands at present. Minor changes are likely as we further improve the system. Not given here are the two other versions: agobs1.asm, to be used with the earlier, slower A/D converter board QADC-2; and agobs3.asm, to be used with an Omega clock.

C-44 Air Gun OBS v.02.00

```

0000          titl   "C-44 Air Gun OBS v.02.00"
              ; ***** 14-Oct-90 ***** for QADC-3
0000          cpu    "8086.TBL/rev" ;CPU table for cross-16
0000          hof    "INT8"      ;Intel 8-bit Hex output format
              ;
              ; ***** Segments, Address Offsets and Port Addresses *****
              ; RAM-2M
01E0 =        intvec: equ    1e0h      ;interrupt vector address
0400 =        shtab:  equ    400h      ;shot table address
FCFC =        ramp:   equ    0fcfch   ;RAM-2M port
              ; CPU-8088
F000 =        board:  equ    0f000h   ;on-board segment
              ; 81C55 RAM, PIO, Timer
0000 =        recno:  equ    0         ;record number
0002 =        blkno:  equ    2         ;block number
0003 =        blks:   equ    3         ;number of blocks
0004 =        chans:  equ    4         ;number of channels
0005 =        sampi:  equ    5         ;sampling interval
0006 =        temp:   equ    6         ;temperature
0008 =        obsno:  equ    8         ;obs number
0009 =        hdrtim: equ    9         ;header time
0010 =        tbuf:   equ    16        ;time buffer start address
0010 =        cdb:    equ    16        ;cdb temporary buffer
001D =        intf:   equ    29        ;interrupt flag
001E =        stptr:  equ    30        ;shot table pointer
0020 =        tabix:  equ    32        ;table entry index (0=pwr-up;1=acq start)
0021 =        bank:   equ    33        ;current bank
0022 =        trcnt:  equ    34        ;tape write retry count
0100 =        stack:  equ    100h     ;top of stack
0400 =        pio:    equ    400h     ;PIO address
0400 =        piocsr: equ    pio      ;command/status register
0401 =        piopa:  equ    pio+1    ;port A
0402 =        piopb:  equ    pio+2    ;port B
0403 =        piopc:  equ    pio+3    ;port C
0404 =        piocl:  equ    pio+4    ;timer count low
0405 =        pioch:  equ    pio+5    ;timer count high
              ; 82C52 UART
4000 =        uart:   equ    4000h   ;UART address
4000 =        urtbr:  equ    uart     ;TBR/RBR transmit/receive buffers
4100 =        urtcs:  equ    uart+100h ;UCR/USR control/status registers
4200 =        urtmc:  equ    uart+200h ;MCR modem control register
4300 =        urtmb:  equ    uart+300h ;BRSR/MSR bit rate select/modem status
              ; 58274 RTC
6000 =        rtc:    equ    6000h   ;RTC address
6000 =        rtccr:  equ    rtc      ;control register
600F =        rtscir: equ    rtc+15   ;clock setting/interrupt registers
              ; QADC-3
2020 =        qadc:   equ    2020h   ;QADC-3 ports base address
2020 =        qadc0:  equ    qadc     ;port 20, data//power off
2222 =        qadc2:  equ    qadc+202h ;port 22, data/convert//power on
2424 =        qadc4:  equ    qadc+404h ;port 24, status 1//gain/channel/convert
2626 =        qadc6:  equ    qadc+606h ;port 26, status 2//convert
2828 =        qadc8:  equ    qadc+808h ;port 28, --//gain/channel
              ; SCSI
6060 =        scsi:   equ    6060h   ;SCSI ports base address

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6060 =      scsi0: equ    scsi      ;data bus/output data
6161 =      scsi1: equ    scsi+101h ;initiator command
6262 =      scsi2: equ    scsi+202h ;mode
6363 =      scsi3: equ    scsi+303h ;target command
6464 =      scsi4: equ    scsi+404h ;bus status/select enable
6565 =      scsi5: equ    scsi+505h ;status/dma send
6666 =      scsi6: equ    scsi+606h ;input data/dma target receive
6767 =      scsi7: equ    scsi+707h ;dma initiator receive/reset
6868 =      dack:  equ   scsi+808h ;dma acknowledge and data output
; wait/hyberstate
8000 =      wait:   equ    8000h   ;wait
A000 =      hybnt:  equ    0a000h  ;hyberstate
; other equivalences
000D =      cr:     equ    0dh    ;carriage return
000A =      lf:     equ    0ah    ;line feed character
;
; ***** Constants *****
C000          org    0c000h
C000 06       c6:    dfb    6
C001 0A       c10:   dfb    10
C002 64       c100:  dfb    100
C003 99       c153:  dfb    153
;
;
; ***** Main Program *****
;
; Initialization
C004 B800F0  init:   mov    ax,#board  ;initialize
C007 8ED8    mov    ds,ax    ; segment registers ds & ss
C009 8ED0    mov    ss,ax    ; to on-board
C00B BC0001  mov    sp,#stack  ;top of stack in 81C55 RAM
C00E E8DF04  call   esram   ;es to ram
C011 B040    mov    al,#40h  ;board 0, 256K bank
C013 BAFCFC  mov    dx,#ramp  ;RAM port
C016 EE      out   dx,al    ;access RAM-2M port
C017 B92000  mov    cx,#32
C01A BE08CA  mov    si,#inttab  ;interrupt vector table
C01D BFE001  mov    di,#intvec ;interrupt vector in ram
C020 F3      rep
C021 A4      movsb
C022 C60600044E mov   [piocsr],#4eh ;copy vector table from eprom to ram
C027 31C0    xor    ax,ax    ;pio A=in, B=C=out, timer=stop
C029 A20204  mov   [piopb],al  ;clear ax
C02C A20304  mov   [piopc],al  ;reset pio O/P B
C02F A30000  mov   [recono],ax ;reset pio O/P C
C032 A30600  mov   [temp],ax  ;reset record number
C035 C60600413C mov   [urtcsl],#3ch ;clear header bytes 6-7
C03A C606004386 mov   [urtbml],#86h ;8-bit, no parity, 1 stop bit
C03F C606004220 mov   [urtmcl],#20h ;9600 baud
C044 C60600600F mov   [rtccrl],#0fh ;receiver enabled
C049 A20F60  mov   [rtcsir],al  ;stop clock & interrupt
C04C C606006005 mov   [rtccr],#5   ;clear interrupt output
C051 C6060F6001 mov   [rtcsir],#1  ;select clock setting register
C056 E82D05  call   rststp  ;select 24-hour mode
C059 BA4ACC  mov   dx,#msgi  ;initialize shot table pointer and idx
C05C E89B04  call   sndmsg  ;output initial message
;
; Main dialog loop
C05F BAA1CC  help:  mov    dx,#menu
C062 E89504  call   sndmsg  ;display command list
C065 E8B704  pro:   call   sndcr
C068 B03E    mov    al,">" ;call   sndchr
C06A E89E04  call   sndchr ;prompt character
C06D E8E304  call   getchr ;get a command character
C070 3C68    cmp    al,"h"  ;help
C072 74EB    je     help
C074 3C63    cmp    al,"c"  ;set clock
C076 741E    je     ciset
C078 3C73    cmp    al,"s"  ;start clock
C07A 744F    je     clstrt
C07C 3C74    cmp    al,"t"  ;display time
C07E 7452    je     dispitm

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C080 3C72      cmp    al,#"r"      ;read in shot table
C082 7453      je     stread
C084 3C64      cmp    al,#"d"      ;display shot table
C086 747F      je     stdisp
C088 3C6D      cmp    al,#"m"      ;data acq./tape drive test
C08A 7407      je     mbr
C08C 3C67      cmp    al,#"g"      ;go
C08E 75D5      jne    pro
C090 E9B501    jmpf   go
C093 E9AF00    mbr:  jmpf   tdtst
;
; Set real time clock
C096 C606006005clset: mov    [rtccr],#5  ;stop clock & interrupt
C09B BA71CC    mov    dx,#msgc  ;clock set prompts
C09E E85404    call   esbrd   ;on-board segment
C0A1 BF0D60    mov    di,#rtc+13 ;start with deca year
C0A4 FD        std    ;and decrement
C0A5 B90600    mov    cx,#6   ;6 2-digit values to set
C0A8 E87404    cloop: call  sndcr  ;crlf
C0AB E84C04    call   sndmsg  ;prompt
C0AE E8B604    call   getnm  ;10's digit
C0B1 AA        stosb
C0B2 E8B204    call   getnm  ;1's digit
C0B5 AA        stosb
C0B6 E2F0        loop  cloop
C0B8 8A450B    mov    al,11[di] ;year
C0BB 2403        and   al,#3   ;leap year index
C0BD D0E0        shlb  al,1
C0BF D0E0        shlb  al,1
C0C1 FEC0        incb  al   ;set 24-hour mode
C0C3 A20F60    mov    [rtcsir],al
C0C6 E82704    call   esram  ;reset es
C0C9 EB9A    jmp   pro
;
; Start real time clock
C0CB C606006001clstrt: mov    [rtccr],#1  ;start clock
C0D0 EB93      jmp   pro
;
; Display time
C0D2 E86E05    disp tm: call  tmdisp  ;display clock time
C0D5 EB8E      jmp   pro
;
; Read in shot table
C0D7 BA91CE    stread: mov   dx,#msgr
C0DA E81D04    call   sndmsg  ;output message
C0DD E88D04    call   gethx  ;obs number
C0E0 A20800    mov   [obsno],al
C0E3 BF0004    mov   di,#shtab ;shot table address
C0E6 FC        cld
C0E7 E8DE04    call   timein ;increment di with store
C0EA E8DB04    rloop: call  timein ;release time
C0ED 3C24        cmp   al,"$"
C0EF 740B    je    rend   ;wake up time
C0F1 E8D404    call   timein ;end of table?
C0F4 E8E904    call   parin  ;start time
C0F7 E8CE04    call   timein ;recording parameters
C0FA EBEE      jmp   rloop  ;stop time
C0FC B00F      rend: mov   al,#0fh
C0FE AA        stosb
C0FF AA        stosb
C100 AA        stosb
C101 E88204    call   rststp ;reset shot table pointer and index
C104 E95EFF    jmpf  pro
;
; Display shot table
C107 BAAFCE    stdisp: mov   dx,#msgt0
C10A E8ED03    call   sndmsg  ;obs no. msg
C10D A00800    mov   al,[obsno]
C110 E82904    call   sndhx  ;shot table address
C113 BE0004    mov   si,#shtab ;increment si with load
C116 FC        cld
C117 BAC2CE    mov   dx,#msgt1

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C11A E8DD03      call  sndmsg      ;release time msg
C11D E8E504      call  disppt      ;display release time
C120 BAD4CE      sloop: mov   dx,#msgt2
C123 E8D403      call  sndmsg      ;wake-up time msg
C126 E8DC04      call  disppt      ;display wake-up time
C129 E8CE03      call  sndmsg      ;record start time msg
C12C E8D604      call  disppt      ;display record start time
C12F E8C803      call  sndmsg      ;parameter msg
C132 E8E304      call  disppt      ;display parameters
C135 E8C203      call  sndmsg      ;stop time msg
C138 E8CA04      call  disppt      ;display stop time
C13B 26          seg   es          ;segment override
C13C 8A04          mov   al,[si]
C13E 3C0F          cmp   al,#0fh    ;last entry?
C140 75DE          jne   sloop      ; no
C142 E920FF          jmpf  pro

;
; Tape drive test
C145 BA36CD      tdtst: mov   dx,#menu
C148 E8AF03      call  sndmsg      ;display drive test menu
C14B C6061D00FE    mov   [intf],#0feh ;direction in case of tape problem
C150 E8CC03      prom: call  sndcr
C153 B02A          mov   al,"**"
C155 E8B303          call  sndchr     ;prompt
C158 E8F803          call  getchr      ;get a command character
C15B 3C68          cmp   al,"h"      ;help
C15D 74E6          je    tdtst
C15F 3C72          cmp   al,"r"      ;read registers
C161 7431          je    rdreg
C163 3C77          cmp   al,"w"      ;write to register
C165 7443          je    wtreg
C167 3C73          cmp   al,"s"      ;select tape drive
C169 744B          je    tsel
C16B 3C70          cmp   al,"p"      ;put cdb
C16D 7465          je    put
C16F 3C67          cmp   al,"g"      ;get data/status/message
C171 747F          je    get
C173 3C69          cmp   al,"i"      ;initialize drive
C175 7444          je    tini
C177 3C6F          cmp   al,"o"      ;output to drive
C179 7445          je    tout
C17B 3C66          cmp   al,"f"      ;write file mark
C17D 744C          je    tfm
C17F 3C61          cmp   al,"a"      ;test acquisition
C181 744D          je    tacqs
C183 3C63          cmp   al,"c"      ;preamp check
C185 744B          je    packs
C187 3C71          cmp   al,"q"      ;quit drive test
C189 75C5          jne   prom

;
C18B E89205      call  ttmpoff     ;turn off tape motor power
C18E E8B705      call  tlppoff     ;turn off tape logic power
C191 E9D1FE      jmpf  pro       ;return to main menu

;
; Read SCSI registers
C194 30C0          rdreg: xor  al,al
C196 E8CB04          rrlp: call screg      ;get scsi register address
C199 50          push  ax
C19A E88B03          call  sndsp      ;space
C19D EC          in   al,dx
C19E E89B03          call  sndhx      ;hex output of register content
C1A1 58          pop   ax
C1A2 FEC0          incb  al
C1A4 3C08          cmp   al,#8
C1A6 75EE          jne   rrlp      ;repeat for 8 registers
C1A8 EBA6          jmp   prom

;
; Write to SCSI register
C1AA E8BA03          wreg: call  getnm      ;get register number
C1AD E8B404          call  screg      ;get scsi register address
C1B0 E8BA03          call  gethx      ;get hex byte
C1B3 EE          out   dx,al      ;write to scsi register

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C1B4 EB9A           jmp    prom
;
; Test select tape drive
C1B6 E8B805         tsel:   call   tdsel
C1B9 EB95           jmp    prom
;
; Test initialize drive
C1BB E8D304         tini:   call   ctnie
C1BE EB90           jmp    prom
;
; Test output to drive
C1C0 E8AA03         tout:   call   gethx      ;get number of blocks in hex
C1C3 A20300          mov    [blk],al
C1C6 E80707          call   write
C1C9 EB85           jmp    prom
;
; Test write file mark
C1CB E8E007         tfm:    call   wref
C1CE EB80           jmp    prom
;
C1D0 EB44           tacqs:  jmp   tacq
C1D2 EB60           packs:  jmp   pack
;
; Put CDB
C1D4 BF1000         put:    mov   di,#cdb      ;CDB address
C1D7 E81B03          call   esbrd      ; on board
C1DA FC              cld
C1DB B90600          mov   cx,#6       ;6-byte CDB
C1DE 51              ptlp:   push  cx
C1DF E88B03          call   gethx      ;get hex byte
C1E2 AA              stosb
C1E3 59              pop   cx
C1E4 E2F8              loop  ptlp
C1E6 E80703          call   esram      ;reset es
C1E9 BE1000          mov   si,#cdb
C1EC E8E005          call   sndcdb      ;output cdb
C1EF E95EFF          jmpf   prom
;
; Get data/status/message
C1F2 BA6464         get:    mov   dx,#scsi4    ;bus status
C1F5 EC              in    al,dx
C1F6 A820             test  al,#20h     ;REQ?
C1F8 7503             jnz   grq        ; yes
C1FA E953FF         jprm:   jmpf  prom      ; no
C1FD A804             test  al,#4       ;input?
C1FF 74F9             jz    jprm
C201 D0E8             shrb  al,1
C203 D0E8             shrb  al,1
C205 2407             and   al,#7       ;isolate phase
C207 BA6363          mov   dx,#scsi3    ; and put in tgt cmd register
C20A EE              out   dx,al
C20B E81A03          call   sndsp      ;output space
C20E E89906          call   getbyt     ;get a byte
C211 E82803          call   sndhx      ;output in hex
C214 EBDC             jmp   get       ;repeat till no input REQ
;
; Test data acquisition
C216 E84E03         tacq:   call   getnm      ;get number of channels
C219 A20400          mov    [chans],al
C21C E84803          call   getnm
C21F E83A01          call   sampic     ;convert to interval count
C222 E84803          call   gethx      ;get number of blocks
C225 A20300          mov   [blk],al
C228 BA79CF          mov   dx,#msgaq
C22B E8CC02          call   sndmsg
C22E E84F01          call   record     ;acquire data
C231 E91CFF          jmpf  prom
;
; ADC power on for preamp check
C234 BA24CF          pack:   mov   dx,#msgpa    ;adc power-on message
C237 E8C002          call   sndmsg
C23A BA2222          mov   dx,#qadc2    ;qadc power-on port

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C23D EE          out  dx,al      ;adc power on
C23E E81203     call  getchr   ;hold till keyboard input
C241 BA2020     mov   dx,#qadc0 ;qadc power-off port
C244 EE          out  dx,al      ;adc power off
C245 E908FF     jmpf  prom

;
; Go
C248 C606006003go: mov   [rtccr],#3  ;select rtc interrupt register
C24D C6060F600F  mov   [rtcsir],#0fh ;60 sec repeated interrupt
C252 BE0360     glp1:  mov   si,#rtc+3 ;point to deca sec
C255 B90300     mov   cx,#3      ;test last 3 digits
C258 E84D03     call  clkud    ;wait for clock update
C25B 803C00     glp2:  cmp   [sil],#0
C25E 75F2        jne   glp1    ;wait till 00.0 sec
C260 4E          decw  si
C261 E2F8        loop  glp2
C263 C606006000 mov   [rtccr],#0  ;start rtc interrupt
C268 E8D803     call  tmdisp   ;display current time
C26B BA55CF     mov   dx,#msggn ;Good night.
C26E E88902     call  sndmsg
C271 C606004202 mov   [urtmc],#2  ;stop uart
C276 C6061D0000gl: mov   [intf],#0
C27B FB          sti
C27C A00080     mov   al,[wait] ;enable cpu interrupt
C27F 90          nop
C280 90          nop
C281 803E1D0000 cmp   [intf],#0  ;test interrupt flag
C286 7CC0        jl   go       ;acq. return - reset rtc interrupt
C288 7FEC        jg   gl       ;non-acq. return - go back to sleep
C28A FA          cli
C28B C606004220 mov   [urtmc],#20h ;restart uart
C290 E8E703     call  dly30    ;wait for uart to settle
C293 E8AD03     call  tmdisp   ;display current time
C296 BA66CF     mov   dx,#msgwu ;wakeup message
C299 E85E02     call  sndmsg
C29C E9C6FD     jmpf  pro

;
;
; ***** Interrupt Service Routines *****
;

; key interrupt service
C29F CF          keyint: iret

;
; rtc interrupt service
C2A0 A00060     rtccint: mov   al,[rtccr] ;clear rtc interrupt flag
C2A3 803E1D0000 cmp   [intf],#0
C2A8 7D03        jge   wkup    ;regular wake up if intf=0
C2AA E9F501     jmpf  twprb   ;otherwise tape write problem
C2AD C606004200wkup: mov   [urtmc],#0
C2B2 E88E03     call  tmdisp   ;start uart with receiver disabled
C2B5 BF0004     mov   di,#shtab ;display current time
C2B8 E89203     call  tmchk   ;release time (mmddhhmm)
C2BB 752B        jne   rels    ;check if release time reached
C2BD 8B3E1E00   mov   di,[stptr] ;shot table entry
C2C1 E88903     call  tmchk   ;check time
C2C4 7415        je    nyst    ;not yet
C2C6 803E200000 cmp   [tabix],#0 ;power up or data acquisition?
C2CB 7530        jnz   dataq   ;data acquisition
C2CD E8BB03     call  ctinit   ;initialize tape drive
C2D0 7509        jnz   nyst    ;initialization failed, try minute later
C2D2 83061E0008 add   [stptr],#8 ;advance shot table pointer
C2D7 FE062000   incb  [tabix] ;and index
C2DB E84102     nyst:  call  sndcr   ;intf>0 for non-acq. interrupt return
C2DE FE061D00   nar:   incb  [intf]
C2E2 C606004202rtir: mov   [urtmc],#2 ;stop uart
C2E7 CF          iret

;
; Release
C2E8 C606030422rels: mov   [piopc],#22h ;release on (pcl & 5 - pins 15 & 16)
C2ED BAB2CF     mov   dx,#msgr1
C2F0 E80702     call  sndmsg
C2F3 E87E03     call  dly10   ;after 15+10 ms

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```

C2F6 C606030400      mov    [piopc],#0      ;release off
C2FB EBE1             jmp    nar
;
; Data acquisition
C2FD BA79CF   dataq:  mov    dx,#msgaq
C300 E8F701             call   sndmsg
C303 C606006001      mov    [rtccr],#1      ;stop rtc interrupt
C308 83061E0008      add    [stptr],#8      ;advance pointer to parameters
C30D 8B3E1E00      mov    di,[stptr]      ;point to shot parameters
C311 FC
C312 26             seg    es
C313 8A05             mov    al,[di]      ;number of channels
C315 A20400            mov    [chans],al
C318 47              incw   di
C319 26             seg    es
C31A 8A05             mov    al,[di]      ;sampling interval
C31C E83D00            call   sampic      ;convert to interval count
C31F 47
C320 26             seg    es
C321 8A05             mov    al,[di]      ;number of blocks
C323 A20300            mov    [blkx],al
C326 83061E0004      add    [stptr],#4      ;advance pointer to stop time
C32B C6061D00FF      mov    [intf],#0ffh     ;intf=-1 for aquisition
C330 E84D00   rcdlp:  call   record      ;acquire a record
C333 8B3E1E00      mov    di,[stptr]      ;point to stop time
C337 E81303            call   tmchk      ;check for stop time
C33A 74F4              je    rcdlp      ;continue with next record
C33C E80403            call   tmdisp      ;display current time
C33F BA95CF            mov    dx,#msgac      ;completion message
C342 E8B501            call   sndmsg
C345 E86606            call   wref      ;write eof
C348 E89806            call   rewind      ;rewind tape
C34B E8D203            call   tmppoff     ;turn off drive motor power
C34E E8F703            call   tlppoff     ;turn off tape logic power
C351 83061E0008      add    [stptr],#8      ;advance pointer to next power-up
C356 C606200000      mov    [tabix],#0      ;clear table index
C35B CF               iret

;
; sampling interval count
C35C A20500            sampic:  mov    [sampi],al
C35F 88C3              mov    bl,al      ;save si temporarily in bl
C361 F62603C0            mulb   [c153]     ;si x 153
C365 93                xchg   ax,bx      ;save in bx and get si
C366 F62600C0            mulb   [c6]       ;si x 6
C36A 050500            add    ax,#5      ;+5
C36D F63601C0            divb   [c10]      ;/10
C371 30E4              xor    ah,ah      ;clear remainder
C373 01D8              add    ax,bx
C375 80CCC0            or     ah,#0c0h     ;set to continuous pulse mode
C378 A20404            mov    [piocl],al
C37B 88260504            mov    [pioch],ah
C37F C3               ret

;
; Acquire a record
C380 BA2222            record:  mov    dx,#qadc2      ;qadc power-on port
C383 EE                 out    dx,al      ;adc power on
C384 BA2424            mov    dx,#qadc4      ;status 1 port
C387 EC               cals:   in     al,dx      ;get status 1
C388 D0C0              rolb   al,1       ;cal bit in c
C38A 73FB              jnc    cals      ;wait for calibration to start
C38C EC               calf:   in     al,dx      ;get status 1
C38D D0C0              rolb   al,1       ;cal bit in c
C38F 72FB              jc    calf      ;wait for calibration to finish
C391 B090              mov    al,#90h      ;bipolar, single-ended, channel 0
C393 BA2828            mov    dx,#qadc8      ;gain/channel port
C396 EE                 out    dx,al      ;select ch 1 low gain
C397 C606210040          mov    [bank],#40h     ;start from bank 0
C39C E8F301            call   rdclk      ;read clock
C39F FF060000            incw   [recno]     ;update record number
C3A3 C606020001          mov    [blkno],#1      ;initialize block number
C3A8 BE1C00            mov    si,#tbuf+12     ;decimal time address
C3AB BF0900            mov    di,#hdrtim    ;header time address

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```

C3AE FD      std
C3AF B90600   mov    cx,#6
C3B2 AC      htlp: lodsb
C3B3 F62601C0 mulb  [c10]      ;convert two decimal digits
C3B7 0204     add   al,[si]    ; to binary
C3B9 8805     mov   [di],al   ; and put in header
C3BB 4E       decw  si
C3BC 47       incw  di
C3BD E2F3     loop  htlp      ;for year, month, day, hour and min.
C3BF 8A04     mov   al,[si]
C3C1 8805     mov   [di],al   ;ds
C3C3 FC       cld
C3C4 B80040   mov   ax,#4000h
C3C7 8EC0     mov   es,ax      ;initial output segment
C3C9 31FF     xor   di,di      ;initial header output offset
C3CB A00004   mov   al,[piocsrl];clear timer flag
C3CE C6060004CE mov   [piocsrl],#0ceh;start timer
C3D3 BAFCF0   bnklp: mov   dx,#ramp   ;RAM-2M port
C3D6 A02100   mov   al,[bank]
C3D9 EE       out   dx,al      ;select bank
C3DA 89F8     blklp: mov   ax,di      ;display block address
C3DC B104     mov   cl,#4
C3DE D3C0     rolw  ax,cl
C3E0 0430     add   al,"0"
C3E2 E82601   call  sndchr
C3E5 31F6     xor   si,si      ;header address
C3E7 B91000   mov   cx,#16
C3EA F3       rep
C3EB A4       movsb
C3EC A00080   aqloop: mov   al,[wait]
C3EF 90       nop
C3F0 A00004   mov   al,[piocsrl]
C3F3 E84200   call  smple
C3F6 F7C7F00F test  di,#0ff0h ;end of block?
C3FA 75F0     jnz   aqloop
C3FC A00200   mov   al,[blkno]
C3FF 3A060300 cmp   al,[blkns]
C403 7420     cmp
C405 FE060200 je    aqcmpl
C409 81FF0000 incb  [blkno]
C40D 75CB     cmp
C40F 8CC0     jne   blklp
C411 F7D8     mov   ax,es
C413 050090   negw ax
C416 8EC0     add   ax,#9000h
C418 3D0050   mov   es,ax      ;change segment
C41B 74BD     cmp   ax,#5000h
C41D 8306210010 je    blklp
C422 E9AEFF   add   [bank],#10h
C425 C60600044Eaqcmpl: jmpf bnklp
C42A BA2020   mov   [piocsrl],#4eh ;stop timer
C42D EE       mov   dx,#qadc0 ;power-off port
C42E E81202   out   dx,al      ;turn off adc power
C431 E8AD00   call  tmdisp
C434 E89904   call  rstsb
C437 C3       call  write
                                ;output data to tape
                                ;
                                ; Sampling with adc
C438 30C9     smple: xor   cl,cl      ;clear channel count
C43A BA2626   loopad: mov   dx,#qadc6 ;convert port
C43D EE       out   dx,al      ;start conversion for low gain
C43E BA2020   mov   dx,#qadc0 ;data port
C441 A20080   mov   [wait],al ;put to wait mode
C444 90       nop
C445 EC       in    al,dx      ;get high byte
C446 88C4     mov   ah,al
C448 EC       in    al,dx      ;get low byte
C449 2D0080   sub   ax,#8000h ;remove offset
C44C 7902     jns   l1
C44E F7D8     negw ax      ;if negative
C450 86C4     l1:  xchg ah,al ;take abs
C452 D1C0     rolw ax,1

```

```

C454 D1C0          rolw  ax,1           ;/16
C456 25FF01        and   ax,#1ffh      ;9 msb
C459 BE46CA        mov   si,#gtab      ;gain table
C45C 01C6          add   si,ax
C45E 8A3C          mov   bh,[si]       ;obtain proper gain
C460 88F8          mov   al,bh
C462 30E4          xor   ah,ah
C464 BE46CC        mov   si,#ctab      ;channel table
C467 01C6          add   si,ax
C469 88C8          mov   al,cl         ;data channel
C46B D0E0          shlb  al,1          ;in bits 1-2
C46D 0A04          or    al,[si]       ;add gain channel bits
C46F BA2828        mov   dx,#qadc8    ;gain/channel port
C472 EE            out   dx,al         ;select proper adc channel
C473 FEC1          incb  cl             ;advance channel count
C475 3A0E0400      cmp   cl,[chans]    ;channels complete?
C479 7C02          jl   12
C47B 30C9          xor   cl,cl
C47D 88CD          mov   ch,cl
C47F D0E5          shlb  ch,1          ;prepare for next data channel
C481 80CD90        or    ch,#90h      ;with bipolar, single-ended, low-gain
C484 BA2424        mov   dx,#qadc4    ;status 1//gain/channel/convert port
C487 EC            13:   in   al,dx       ;get status 1
C488 2408          and   al,#8
C48A 75FB          jne   13
C48C 88E8          mov   al,ch
C48E EE            out   dx,al         ;next low-gain channel
C48F A20080        mov   [wait],al    ;select next channel and start conversion
C492 90            nop
C493 BA2020        mov   dx,#qadc0    ;put to wait mode
C496 EC            in   al,dx       ;data port
C497 88C4          mov   ah,al       ;get high byte
C499 EC            in   al,dx       ;get low byte and start conversion
C49A 08F8          or    al,bh
C49C AB            stosw
C49D 08C9          or    cl,cl
C49F 7599          jne   loopad     ;last channel?
C4A1 C3            ret
;
; Tape write problem - abort
C4A2 C606006001twprb: mov  [rtccr],#1  ;stop rtc interrupt
C4A7 E83700        call  rstsb      ;reset segment reg. & bank
C4AA E8B602        call  rstsc      ;reset SCSI bus
C4AD BC0001        mov   sp,#stack  ;reset stack pointer
C4B0 BAA7D0        mov   dx,#msgto  ;timeout abort message
C4B3 E84400        call  sndmsg
C4B6 803E1D00FF    cmp   [intf],#0ffh
C4BB 7403          je    rtng
C4BD E990FC        jmpf  prom      ;return to 2nd menu prompt
C4C0 832E1E000Crtng: sub   [stptr],#12 ;roll back shot table pointer
C4C5 E98AFD        jmpf  glp1      ;go back to sleep
;
; ADC interrupt
C4C8 CF            adcint:  iret
;
; Sampling interrupt
C4C9 CF            smpint:  iret
;
; Misdirected interrupts
C4CA B032          md2int:  mov   al,"2"
C4CC EB0A          jmp   bimsg
C4CE B033          md3int:  mov   al,"3"
C4D0 EB06          jmp   bimsg
C4D2 B036          md6int:  mov   al,"6"
C4D4 EB02          jmp   bimsg
C4D6 B037          md7int:  mov   al,"7"
C4D8 E83000        bimsg:   call  sndchr
C4DB BAC4CF        mov   dx,#msgmi
C4DE E81900        call  sndmsg
;
;
; ***** Subroutines *****

```

```

;
; Reset ds(on-board), es(RAM-2M) and bank(0)
C4E1 E80C00    rstsb: call  esram           ;set es to ram
C4E4 BAFCF0    mov    dx,#ramp          ;RAM port
C4E7 B040      mov    al,#40h          ;board 0, 256K bank
C4E9 EE        out   dx,al           ;access RAM-2M port at bank 0
C4EA B800F0    mov    ax,#board
C4ED 8ED8      mov    ds,ax           ;set ds to on-board
C4EF C3        ret

;
; Set es to ram
C4F0 31C0      esram: xor   ax,ax
C4F2 8EC0      esl:   mov   es,ax
C4F4 C3        ret

;
; Set es to on-board
C4F5 B800F0    esbrd: mov   ax,#board
C4F8 EBF8      jmp   esl

;
; Send a message (@dx) out to UART
C4FA 87D6      sndmsg: xchg  si,dx
C4FC 8A04      mloop: mov   al,[si]       ;get a character
C4FE 46        incw   si
C4FF 3C24      cmp   al,"$"         ;terminator?
C501 7405      je    mout          ;yes
C503 E80500    call   sndchr        ;output a character
C506 EBF4      jmp   mloop
C508 87F2      mout: xchg  dx,si
C50A C3        ret

;
; Send a character (in al) out to UART
C50B A20040    sndchr: mov   [urtbr],al     ;send a character
C50E A00041    swt:   mov   al,[urtcs]    ;get status
C511 D0C0      rolb   al,1           ;any data left over?
C513 7305      jnc    scl            ;no
C515 A00040    mov   al,[urtbr]     ;yes, discard it
C518 EBF4      jmp   swt
C51A 2440      scl:   and   al,#40h     ;complete?
C51C 74F0      je    swt            ;wait till complete
C51E C3        ret

;
; Send CR & LF out ot UART
C51F B00D      sndcr: mov   al,#cr        ;CR
C521 E8E7FF    call   sndchr
C524 B00A      mov   al,#lf        ;LF
C526 EBE3      jmp   sndchr

;
; Send space
C528 B020      sndsp: mov   al," "
C52A EBDF      jmp   sndchr

;
; Send numeric character
C52C 0430      sndnm: add   al,#"0"      ;convert to ASCII
C52E EBDB      jmp   sndchr

;
; Send space or numeral
C530 08C9      sndsn: or    cl,cl
C532 75F8      jne   sndnm          ;leading non-zero
C534 08C0      or    al,al
C536 74F0      je    sndsp          ;zero - send space
C538 FEC1      incb  cl            ;set non-zero flag
C53A EBFO      jmp   sndnm          ;non-zero - send numeral

;
; Send hex characters
C53C 50        sndhx: push  ax
C53D B104      mov   cl,#4
C53F D2F8      sarb  al,cl
C541 E80500    call   hexout
C544 58        pop   ax
C545 E80100    call   hexout
C548 C3        ret
C549 240F      hexout: and  al,#0fh

```

```

C54B 3C09      cmp    al,#9
C54D 7EDD      jle    sndnm
C54F 0407      add    al,#7
C551 EBD9      jmp    sndnm
;
; Get a character (in al) from UART
C553 A00041    getchr: mov   al,[urtcs] ;get status
C556 D0C0      rolb   al,1      ;data ready?
C558 73F9      jnc    getchr  ;no, wait till data ready
C55A A00040    mov   al,[urtbr] ;get the character
C55D 3C74      cmp    al,#"t"
C55F 7405      je     grtn   ;no echo if "t"
C561 50        push   ax
C562 E8A6FF    call   sndchr ;echo
C565 58        pop    ax
C566 C3        grtn: ret
;
; Get a character and convert to numeric
C567 E8E9FF    getnm: call   getchr ;get a character
C56A 2C30      sub    al,#"0"  ;convert to binary
C56C C3        ret
;
; Get hex characters and convert to binary
C56D E80C00    gethx: call   hexin
C570 B104      mov    cl,#4
C572 D2E0      shlb   al,cl
C574 88C1      mov    cl,al
C576 E80300    call   hexin
C579 08C8      or    al,cl
C57B C3        ret
C57C E8E8FF    hexin: call   getnm
C57F 3C09      cmp    al,#9
C581 7E02      jle    hx rtn
C583 2C27      sub    al,#39
C585 C3        hx rtn: ret
;
; Reset shot table pointer
C586 C7061E0008rststp: mov   [stptr],#shtab+8 ;first shot group
C58C C606200000 mov   [tabix],#0   ;reset index
C591 C3        ret
;
; Read clock
C592 BE0D60    rdclk: mov   si,#rtc+13 ;start with deca year
C595 BF1C00    mov   di,#tbuf+12 ;time buffer in RAM
C598 E85AFF    call   esbrd  ;es on board
C59B FD        std
C59C B90D00    mov   cx,#13  ;and decrement
C59F E80600    call   clkud  ;for 13 bytes
C5A2 F3        rep
C5A3 A4        movsb
C5A4 E849FF    call   esram  ;get clock data
C5A7 C3        ret
;
; Wait for clock update
C5A8 A00060    clkud: mov   al,[rtccr] ;reset control reg
C5AB A00060    wtupd: mov   al,[rtccr]
C5AE 2408      and   al,#8   ;test for DCF
C5B0 74F9      je    wtupd  ;wait for update
C5B2 C3        ret
;
; Display clock time
C5B3 B054      dispck: mov   al,#"T"
C5B5 E853FF    call   sndchr ;signal start of time data
C5B8 BE1C00    mov   si,#tbuf+12 ;start with deca year
C5BB B90D00    mov   cx,#13  ;and for 13 bytes
C5BE AC        dloop: lodsb ;get a byte
C5BF E86AFF    call   sndnm ;and output
C5C2 E2FA      loop   dloop
C5C4 E861FF    call   sndsp
C5C7 C3        ret
;
; Table time input

```

```

C5C8 E854FF    timein: call  sndcr
C5CB E885FF    tloop:  call  getchr      ;get a character
C5CE 3C24       cmp   al,"$"
C5D0 740D       je    tirthn      ;return if end of table
C5D2 3C20       cmp   al," "
C5D4 74F5       je    tloop        ;skip if space
C5D6 3C0D       cmp   al,#cr
C5D8 7405       je    tirthn      ;return if cr
C5DA 2C30       sub   al,"0"       ;convert to binary
C5DC AA         stosb      ;and store
C5DD EBEC       jmp   tloop
C5DF C3         tirthn: ret
; Table parameter input
C5E0 E83CFF    parin:  call  sndcr
C5E3 31D2       ploop: xor  dx,dx      ;clear dx
C5E5 E86BFF    ploop2: call  getchr      ;get a character
C5E8 3C2C       cmp   al,","
C5EA 7410       je    pout        ;if comma, store parameter
C5EC 3C0D       cmp   al,#cr
C5EE 7411       je    pout2       ;if cr, store par. and return
C5F0 2C30       sub   al,"0"       ;convert to binary
C5F2 86D0       xchg  al,d1      ;save in dl and get dl
C5F4 F62601C0  mulb  [c10]      ;multiply previous value by 10
C5F8 01C2       add   dx,ax      ;and add to new digit
C5FA EBE9       jmp   ploop2
C5FC 88D0       pout:  mov   al,d1
C5FE AA         stosb      ;save binary byte
C5FF EBE2       jmp   ploop
C601 89D0       pout2: mov   ax,dx
C603 AB         stosw      ;save binary word
C604 C3         ret
;
; Dipsplay shot table time
C605 B90400    disptt: mov  cx,#4
C608 E81DFF    dtloop: call  sndsp
C60B 26         seg   es          ;override segment es for input
C60C AD         lodsw      ;get two bytes
C60D E81CFF    call  sndnm      ;output first numeral
C610 88E0       mov   al,ah
C612 E817FF    call  sndnm      ;output second numeral
C615 E2F1       loop  dtloop      ;repeat for 4 sets of numerals
C617 C3         ret
;
; Display shot table parameters
C618 E80700    disp:  call  decb      ;output sample rate
C61B E80400    call  decb      ;output number of channels
C61E 26         seg   es
C61F AD         lodsw      ;get two-byte number of blocks
C620 EB04       jmp   decpr      ;and output
C622 26         decb:  seg   es
C623 AC         lodsb      ;get a byte
C624 30E4       xor   ah,ah      ;clear ah
C626 30C9       decpr: xor  cl,cl      ;clear none-zero flag
C628 F63602C0  divb  [c100]     ;100's digit
C62C E801FF    call  sndsn      ;space or numeral
C62F 88E0       mov   al,ah      ;remainder
C631 30E4       xor   ah,ah      ;clear ah
C633 F63601C0  divb  [c10]      ;10's digit
C637 E8F6FE    call  sndsn
C63A 88E0       mov   al,ah      ;1's digit
C63C E8EDFE    call  sndnm
C63F E8E6FE    call  sndsp
C642 C3         ret
;
; Time display
C643 E84CFF    tmdisp: call  rdclk     ;read clock
C646 E86AFF    call  dispck     ;display clock time
C649 E82800    call  dly10      ;wait 10 ms for possible clock output
C64C C3         ret
;
; time check - zero flag cleared if time reached or passed
C64D BE0B60    tmchk:  mov   si,#rtc+11  ;current time (mmddhhmm)

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```

C650 FC          cld      ;mo->min
C651 30C0        xor     al,al   ;clear flag
C653 B90800      mov     cx,#8    ;up to 8 digits to test
C656 A6          tclp:   cmpsb   ;check time
C657 7C08        jl      ny      ;not yet
C659 7F04        jg      psd     ;passed
C65B 4E          decw   si
C65C 4E          decw   si
C65D E2F7        loop   tclp
C65F FEC0        psd:   incb   al      ;time reached or passed, set flag
C661 08C0        ny:   or     al,al   ;set/reset zero flag
C663 C3          ret
;
; SCSI register I/O address
C664 BA6060      screg:  mov    dx,#scsi
C667 00C6        add    dh,al
C669 00C2        add    dl,al
C66B C3          ret
;
; 25 us delay
C66C 51          wt25:  push   cx
C66D B90200      mov    cx,#2
C670 E2FE        lp25:  loop   lp25
C672 59          pop    cx
C673 C3          ret
;
; 10 ms delay
C674 51          dly10: push   cx
C675 B94D01      mov    cx,#333
C678 EB04        jmp    dllp
;
; 30 ms delay
C67A 51          dly30: push   cx
C67B B9B703      mov    cx,#999
C67E 50          dllp:  push   ax
C67F D40A        aam
C681 58          pop    ax
C682 E2FA        loop   dllp   ;30.3 us/loop
C684 59          pop    cx
C685 C3          ret
;
; 2 sec delay
C686 51          dly2s: push   cx
C687 31C9        xor    cx,cx
C689 EBF3        jmp    dllp
;
;
; ***** Cartridge Tape Driver Subroutines *****
;
; Initialize cartridge tape drive
C68B BA66CF      ctinit: mov    dx,#msgwu
C68E E869FE      call   sndmsg
C691 E82800      ctinie: call   tmpon   ;turn on tape motor power
C694 7525        jnz    cirtn   ;no motor power
C696 E85600      call   tlpon   ;turn on tape logic power
C699 7520        jnz    cirtn   ;no logic power
C69B BA3ED0      mov    dx,#msgit
C69E E859FE      call   sndmsg
C6A1 E8BF00      call   rstsc   ;reset SCSI bus
C6A4 E8DFFF      call   dly2s   ;wait for 2 s
C6A7 E8C700      call   tdsel   ;select tape drive
C6AA 750F        jnz    cirtn   ;select error
C6AC E8F100      call   turdy   ;take care of unit attention
C6AF E8BF00      call   tdsel   ;select drive again
C6B2 7507        jnz    cirtn   ;select error
C6B4 E8F800      call   enddat  ;skip to end of data
C6B7 7502        jnz    cirtn   ;failed to find end of data
C6B9             pwoff:; call   tmpoff  ;turn off tape motor power
C6B9 30C0        xor    al,al   ;clear error flag
C6BB C3          cirtn: ret
;
; Turn on tape drive motor power
C6BC B90A00      tmpon: mov    cx,#10   ;retry count

```

```

C6BF C606020402mplp:    mov    [piopb],#2      ;motor power on (pb1 - pin 31)
C6C4 E8B3FF    call   dly30      ;wait 30 ms
C6C7 F606010402  test  [piopa],#2      ;sense motor power (pa1 - pin 30)
C6CC 750A    jnz   m1        ;not on
C6CE BADCCF    mov    dx,#msgpu
C6D1 E826FE    call   sndmsg
C6D4 30C0    xor   al,al      ;on, clear error flag
C6D6 EB11    jmp   tprtn
C6D8 C606020408ml:    mov    [piopb],#8      ;motor power off (pb3 - pin 27)
C6DD E89AFF    call   dly30      ;wait 30 ms
C6E0 E2DD    loop  mplp      ;try again
C6E2 BAC4D0    mov    dx,#msge1      ;error 1 message (no motor power)
C6E5 E812FE em1:    call   sndmsg
C6E8 42     sf1:    incw  dx        ;set error flag
C6E9 C606020400tp rtn:    mov    [piopb],#0      ;clear tape power command
C6EE C3     ret

;
; Turn on tape drive logic power
C6EF B90A00 tlp on:    mov    cx,#10      ;retry count
C6F2 C6060204201plp:    mov    [piopb],#20h      ;logic power on (pb5 - pin 23)
C6F7 E880FF    call   dly30      ;wait 30 ms
C6FA F606010420  test  [piopa],#20h      ;sense logic power (pa5 - pin 22)
C6FF 750A    jnz   lg1        ;not on
C701 BAF4CF    mov    dx,#msglu
C704 E8F3FD    call   sndmsg
C707 30C0    xor   al,al      ;on, clear error flag
C709 EBDE    jmp   tprtn
C70B C6060204801gl1:    mov    [piopb],#80h      ;logic power off (pib7 - pin 19)
C710 E867FF    call   dly30      ;wait 30 ms
C713 E2DD    loop  lplp      ;try again
C715 BADBDO    mov    dx,#msge2      ;error 2 message (no logic power)
C718 E8DFFD em2:    call   sndmsg
C71B E80200  call   tmppoff      ;turn off tape motor power
C71E EBC8    jmp   sf1        ;set error flag and return
;
; Turn off tape drive motor power
C720 F606010420tmppoff: test  [piopa],#20h      ;logic power on?
C725 7503    jnz   n1        ;no
C727 E85cff    call   dly2s      ;if logic power on, wait 2 s
C72A B93629 n1:    mov    cx,#10550      ;200 ms time out count
C72D C606020408mplp:    mov    [piopb],#8      ;motor power off (pb3 - pin 27)
C732 F606010402  test  [piopa],#2      ;sense motor power (pa1 - pin 30)
C737 7507    jnz   n2        ;power is now off
C739 E2F2    loop  molp      ;wait till power off, 18.76 us/loop
C73B BAF2D0    mov    dx,#msge3      ;error 3 message (motor power left on)
C73E EB03    jmp   n3
C740 BA0CD0 n2:    mov    dx,#msgpd
C743 E8B4FD n3:    call   sndmsg
C746 EBA1    jmp   tprtn
;
; Turn off tape drive logic power
C748 B93629 tlp off:    mov    cx,#10550      ;200 ms time out count
C74B C6060204801lop:    mov    [piopb],#80h      ;logic power off (pb3 - pin 27)
C750 F606010420  test  [piopa],#20h      ;sense logic power (pa5 - pin 22)
C755 7507    jnz   n4        ;power is now off
C757 E2F2    loop  lolp      ;wait till power off, 18.76 us/loop
C759 BA09D1    mov    dx,#msge4      ;error 4 message (logic power left on)
C75C EBES    jmp   n3
C75E BA25D0 n4:    mov    dx,#msgld
C761 EBE0    jmp   n3
;
; Reset SCSI bus
C763 B080 rstsc:    mov    al,#80h      ;assert RST
C765 BA6161  mov    dx,#scsil      ;to initiator command register
C768 EE     out   dx,al
C769 B008    mov    al,#8
C76B FEC8 dlpl:    decb  al
C76D 75FC    jnz   dlpl1      ;40 us delay
C76F EE     out   dx,al      ;deassert RST
C770 C3     ret

;
; Select tape drive

```

```

C771 E88400    tdsel:  call  bfpshs      ;get bus-free phase
C774 7518       jnz   dserr        ;no bus-free phase
C776 B041       mov   al,#41h      ;initiator(6) and target(0) ID's
C778 BA6060      mov   dx,#scsi0     ; to output data register
C77B EE          out   dx,al
C77C B005       mov   al,#5       ;assert SEL & DATA BUS
C77E BA6161      mov   dx,#scsil     ; to initiator command register
C781 EE          out   dx,al
C782 31C9       xor   cx,cx      ;timeout count
C784 BA6464      tolpl: mov  dx,#scsi4     ;current scsi bus status
C787 EC          in    al,dx
C788 A840       test  al,#40h      ;BSY set?
C78A 7507       jnz   sel         ; yes - selected
C78C E2F6       loop  tolpl
C78E BA20D1      dserr: mov  dx,#msg5      ;550 ms timeout loop
C791 EB85       jmp   em2         ;error 5 message (drive select error)
C793 BA59D0      sel:  mov  dx,#msgds     ;turn off motor, set flag and return
C796 E861FD      call  sndmsg
C799 30C0       xor   al,al      ;deassert SEL & DATA BUS
C79B BA6161      mov   dx,#scsil     ; in initiator command register
C79E EE          out   dx,al
C79F C3          ret
;
; Test if tape drive ready
C7A0 BE28CA      turdy: mov  si,#urcdb     ;test unit ready CDB
C7A3 E82900      call  sndcdb      ;send command to tape drive
C7A6 7506       jnz   turtn      ;phase mismatch
C7A8 BB0100      mov   bx,#1       ;timeout count
C7AB E8D600      call  status      ;get status
C7AE C3          turtn: ret
;
; Skip to end of data
C7AF BE2ECA      enddat: mov  si,#edcddb   ;space to end of data CDB
C7B2 E81A00      call  sndcddb     ;send command to tape drive
C7B5 750F       jnz   ederr       ;phase mismatch
C7B7 BB9501      mov   bx,#405      ;timeout count (5 min)
C7BA E8C700      call  status      ;get status
C7BD 7507       jnz   ederr       ;failed to find end of data
C7BF BA6BD0      mov   dx,#msgend    ;end of data message
C7C2 E835FD      call  sndmsg
C7C5 C3          ret
C7C6 BA36D1      ederr:  mov  dx,#msg6      ;error 6 message (failed to find eod)
C7C9 E8BAFE      call  dly2s       ;wait 2 sec
C7CC E949FF      jmpf  em2         ;turn off motor, set flag and return
;
; Send a command descriptor block to tape drive
C7CF E88B00      sndcddb: call cmdphs      ;command phase?
C7D2 746B       jz    pmm         ; no, phase mismatch
C7D4 B90600      mov   cx,#6       ;byte count
;
; Send command or data [address in si; byte count in cx]
C7D7 E8E400      sndcd:  call reqas      ;wait for REQ
C7DA BA6565      mov   dx,#scsi5     ;bus and status register
C7DD EC          in    al,dx
C7DE A808       test  al,#8       ;phase matched?
C7E0 745D       jz    pmm         ; no, phase mismatched
C7E2 FC          cld
C7E3 AC          lodsb
C7E4 BA6060      mov   dx,#scsi0     ;command/data byte
C7E7 EE          out   dx,al      ; to output data register
C7E8 B019       mov   al,#19h      ;assert ACK, BSY & DATA BUS
C7EA BA6161      mov   dx,#scsil     ; in initiator command register
C7ED EE          out   dx,al
C7EE E8D600      call  reqda      ;wait for no REQ
C7F1 BA6161      mov   dx,#scsil
C7F4 EE          out   dx,al      ;deassert ACK & DATA BUS
C7F5 E2E0       loop  sndcd
C7F7 C3          ret
;
; Get bus-free phase
C7F8 31C9       bfpshs: xor  cx,cx      ;timeout count
C7FA BA6464      tolpl2: mov  dx,#scsi4    ;current SCSI bus status

```

```

C7FD EC      in    al,dx
C7FE 24FE    and   al,#0feh ;bus-free?
C800 7505    jnz   bf1
C802 BA6363  mov   dx,#scsi3
C805 EE      out   dx,al  ;clear mode register
C806 C3      ret
C807 A820    bfl: test  al,#20h ;REQ active?
C809 750E    jnz   bf2
C80B E2ED    loop  tolpx
C80D E82CFD  call   sndhx
C810 E815FD  call   sndsp
C813 BA54D1  mov   dx,#msge7 ;error 7 message (no bus-free phase)
C816 E9CCFE  jmpf  em1
C819 D0E8    bf2: shrb  al,1
C81B D0E8    shrb  al,1  ;shift right 2
C81D 2407    and   al,#7   ;isolate phase bits
C81F BA6363  mov   dx,#scsi3
C822 EE      out   dx,al  ; place phase bits in mode register
C823 BA6060  mov   dx,#scsi0 ; for the next step
C826 A801    test  al,#1  ;input?
C828 7405    jz    bf3
C82A EC      in    al,dx ; no, output
C82B B018    mov   al,#18h ; yes, get it (and discard it)
C82D EB03    jmp   bf4
C82F EE      out   dx,al  ; and assert ACK & BSY
C830 B019    mov   al,#19h
C832 BA6161  bf4: mov   dx,#scsil
C835 EE      out   dx,al  ; in initiator command register
C836 E88E00  call   reqda
C839 BA6161  mov   dx,#scsil
C83C EE      out   dx,al  ;wait for no REQ
C83D EBB9    jmp   bfphs ;deassert ACK
;repeat
;
; Phase mismatch message
pmm:  mov   dx,#msge8 ;error 8 message (phase mismatch)
call   sndmsg
mov   dx,#scsi3
in    al,dx
call   sndnm
call   sndsp
mov   dx,#scsi4 ;bus status register
;
pmx:  xor   al,al ;z for phase mismatch
ret
;
; Test for data-out phase
dophs: xor   al,al ;none for data-out phase
jmp   phstst ;test for data-out phase
;
; Test for command phase
cmdphs: mov   al,#2 ;C/D for command phase
jmp   phstst ;test for command phase
;
; Test for status phase
stphs: mov   al,#3 ;C/D & I/O for status phase
jmp   phstst ;test for correct phase
;
; Test for message-in phase
miphs: mov   al,#7 ;MSG, C/D & I/O for message-out phse
;
; Test phase
phstst: mov   dx,#scsi3
out   dx,al
xor   cx,cx
;phase bits in target command register
;timeout count
tolpx: mov   dx,#scsi4
in    al,dx
and   al,#0feh ;current SCSI bus status
jz    ptrtn ;bus free?
test  al,#20h ;yes, return
jnz   ph1 ;REQ?
loop  tolpx ;yes
;0.74 s timeout loop

```

```

C87B EBD9      jmp   pmx      ;mismatched (z)
C87D BA6565    ph1:  mov   dx, #scsi5
C880 EC        in    al,dx   ;bus and status register
C881 2408      and   al,#8   ;phase matched?
C883 C3        ptrtn: ret   ;nz if matched, z if mismatched
;
; Get status and message from drive
C884 E8DAFF    status: call  stphs   ;test for status phase
C887 7410      jz    spmm    ;phase mismatch
C889 E81E00    call  getbyt  ;get status
C88C 50        push  ax     ;save status
C88D E8D5FF    msgip: call  miphis  ;test for message-in phase
C890 7410      jz    mpmm    ;phase mismatch
C892 E81500    call  getbyt  ;get message and discard
C895 58        pops: pop   ax     ;restore status
C896 240A      and   al,#0ah ;error?
C898 C3        ret
C899 4B        spmm: decw  bx     ;timeout count down
C89A 75E8      jnz   status
C89C E8A0FF    call  pmm    ;send phase mismatch message
C89F FEC0      incb  al     ;phase mismatch, code=01
C8A1 C3        ret
C8A2 4B        mpmm: decw  bx     ;timeout count down
C8A3 75E8      jnz   msgip
C8A5 E897FF    call  pmm    ;send phase mismatch message
C8A8 EBEB      jmp   pops   ;restore status and return
;
; Get a byte
C8AA BA6060    getbyt: mov   dx, #scsi0
C8AD EC        in    al,dx   ;read current SCSI data
C8AE 50        push  ax     ;save the data
C8AF B018      mov   al, #18h ;assert ACK & BSY
C8B1 BA6161    mov   dx, #scsil ;in initiator command register
C8B4 EE        out   dx,al
C8B5 E80F00    call  reqda ;wait for no REQ
C8B8 BA6161    mov   dx, #scsil
C8BB EE        out   dx,al   ;deassert ACK
C8BC 58        pop   ax
C8BD C3        ret
;
; Wait for REQ assertion
C8BE BA6464    reqas: mov   dx, #scsi4
C8C1 EC        in    al,dx   ;get current SCSI bus status
C8C2 A820      test  al, #20h ;REQ asserted?
C8C4 74F8      jz    reqas   ;wait for REQ
C8C6 C3        ret
;
; Wait for REQ deassertion
C8C7 BA6464    reqda: mov   dx, #scsi4
C8CA EC        in    al,dx   ;get current SCSI bus status
C8CB 2420      and   al, #20h ;REQ deasserted?
C8CD 75F8      jnz   reqda   ;wait for no REQ
C8CF C3        ret
;
; Send data out to tape drive in pseudo DMA mode
C8D0 C606220003 write: mov   [trcnt], #3 ; 3 trials in case of problem
C8D5 C60600603    mov   [rtccr], #3 ;select rtc interrupt register
C8DA C6060F6006   mov   [rtcsir], #6 ;30 sec timeout (single interrupt)
C8DF wtlp:: call  tmpon ;turn on tape motor power
; jnz   wl   ;power on failed
; call  tdsel ;select tape drive
C8DF E88FFE    w1:  jmpf  wrerr ; drive not selected
C8E2 7403      w2:  mov   si, #wrcdb ;write CDB
C8E4 E9B200    w1:  jmpf  wrerr ; temporary CDB buffer
C8E7 BE34CA    w2:  mov   si, #cdb ;set es to on-board
C8EA BF1000    mov   di, #cdb
C8ED E805FC    call  esbrd
C8F0 FC        cld
C8F1 B90600    mov   cx, #6   ;6-byte cdb
C8F4 F3        rep
C8F5 A4        movsb
C8F6 B740      mov   bh, #40h ;copy write CDB to cdb buffer
C8F8 A00300    mov   al, [blk] ;start with bank 0
; number of input (4K) blocks

```

```

C8FB 88C3          mov bl,al           ;block counter
C8FD 30E4          xor ah,ah
C8FF D1E0          shlw ax,1
C901 D1E0          shlw ax,1
C903 D1E0          shlw ax,1
C905 88261300      mov [cdb+3],ah   ;number of output (0.5K) blocks
C909 A21400         mov [cdb+4],al   ; in cdb
C90C BE1000         mov si,#cdb    ;send write command
C90F E8BDDE        call sndcdb     ; to tape drive
C912 75D0          jnz wl        ; phase mismatch
C914 E842FF        call dophs     ;test for data-out phase
C917 74CB          jz wl        ; phase mismatch
C919 C606006000    mov [rtcrr],#0  ;start rtc interrupt
C91E FB            sti           ;enable cpu interrupt
C91F 31F6          xor si,si     ;data start offset
C921 B80040         mov ax,#4000h  ;first segment
C924 8EC0          mov es,ax
C926 B009          mov al,#9     ;assert BSY & DATA BUS
C928 BA6161         mov dx,#scsil  ; in initiator command register
C92B EE            out dx,al
C92C B002          mov al,#2     ;DMA mode
C92E BA6262         mov dx,#scsi2  ; to mode register
C931 EE            out dx,al
C932 BA6565         mov dx,#scsi5
C935 EE            out dx,al
C936 88F8          wrlp1:      mov al,bh
C938 BAFCF0         mov dx,#ramp
C93B EE            out dx,al
C93C BA6868         mov dx,#dack
C93F B90004         wrlp2:      mov cx,#400h
C942 26            wrlp3:      seg es
C943 AC            lodsb
C944 A20080         mov [wait],al  ;get a data byte
C947 90            nop          ;wait for DRQ interrupt (wake up)
C948 EE            out dx,al   ;output data to tape
C949 26            seg es
C94A AC            lodsb
C94B A20080         mov [wait],al  ;second
C94E 90            nop          ; byte
C94F EE            out dx,al   ; output
C950 26            seg es
C951 AC            lodsb
C952 A20080         mov [wait],al  ;third
C955 90            nop          ; byte
C956 EE            out dx,al   ; output
C957 26            seg es
C958 AC            lodsb
C959 A20080         mov [wait],al  ;fourth
C95C 90            nop          ; byte
C95D EE            out dx,al   ; output
C95E E2E2          loop wrlp3
C960 FECB          decb bl
C962 7419          jz wrcmpl
C964 81FE0000      cmp si,#0
C968 75D5          jne wrlp2
C96A 8CC0          mov ax,es
C96C F7D8          negw ax
C96E 050090         add ax,#9000h
C971 8EC0          mov es,ax
C973 3D0050         cmp ax,#5000h
C976 74C7          je wrlp2
C978 80C710         add bh,#10h
C97B EBB9          jmp wrlp1
C97D 30C0          wrmpl:    xor al,al
C97F BA6161         mov dx,#scsil  ;turn off
C982 EE            out dx,al   ; assert DATA BUS
C983 BA6262         mov dx,#scsi2  ; in initiator command register
C986 EE            out dx,al   ; and DMA MODE
C987 E857FB         call rstsb
C98A FA            cli           ; in mode register
C98B C606006001    mov [rtcrr],#1 ;reset segment registers and bank
C990 BB1B00         mov bx,#27  ;disable cpu interrupt
                                ;stop rtc interrupt
                                ;20 s timeout

```

```

C993 E8EEFE      call  status      ;get status
C996 7501        jnz   wrerr      ;no status
                  ;call  tmppoff    ;turn off tape motor power
C998 C3          wrret: ret
C999 E845FB      wrerr: call  rstsb      ;reset segment registers and bank
C99C BA84D1      mov   dx,#msge9  ;error 9 message (write error)
C99F E858FB      call  sndmsg
C9A2 FE0E2200    decb  [trcnt]   ;count down retry count
C9A6 74F0         je    wret       ;retry count exceeded
C9A8 E8E6FC      call  ctinie    ;reinitialize tape drive
C9AB E931FF      jmpf  wtlp       ; and try again
;
; Write file mark
C9AE C606220003wreof: mov   [trcnt],#3  ;at most 3 retries
C9B3 E806FD      wfip:  call  tmpon     ;turn on drive motor power
C9B6 E8B8FD      call  tdsel     ;select tape drive
C9B9 7517         jnz   eferr      ; drive not selected
C9BB BE3ACA      mov   si,#fmcdcb  ;write file mark CDB
C9BE E80EFE      call  sndcdb    ;send command to tape drive
C9C1 750F         jnz   eferr      ; phase mismatch
C9C3 BB0E00      mov   bx,#14     ;10 s timeout
C9C6 E8BBFE      call  status     ;get status and message
C9C9 7507         jnz   eferr      ;eof write error
C9CB BA85D0      mov   dx,#msgfm  ;eof message
C9CE E829FB      call  sndmsg
                  ;call  tmppoff    ;turn off drive motor power
C9D1 C3          fret:  ret
C9D2 BA9ED1      eferr: mov   dx,#msge10  ;error 10 message (eof error)
C9D5 E822FB      call  sndmsg
C9D8 FE0E2200    decb  [trcnt]   ;count down retry count
C9DC 74F3         je    fret       ;retry count exceeded
C9DE E8B0FC      call  ctinie    ;reinitialize tape drive
C9E1 EBDD0        jmp   wflp       ; and try again
;
; Resind tape
C9E3 E8D6FC      rewind: call  tmpon    ;turn on drive motor power
C9E6 E888FD      call  tdsel     ;select tape drive
C9E9 7516         jne   rwerr      ;drive not selected
C9EB BA9AD0      mov   dx,#msgrw  ;rewinding message
C9EE E809FB      call  sndmsg
C9F1 BE40CA      mov   si,#rwcdb  ;rewind CDB
C9F4 E8D8FD      call  sndcdb    ; to tape drive
C9F7 7508         jne   rwerr      ;phase mismatch
C9F9 BBF300      mov   bx,#243   ;3 min timeout
C9FC E885FE      call  status     ;get status and message
C9FF 7406         je    rwrttn    ;get status and message
CA01 BAB7D1      rwerr: mov   dx,#msgell  ;error 11 message (rwd error)
CA04 E8F3FA      call  sndmsg
CA07 C3          rwrttn: ret
;
; ***** Tables and Messages *****
;
; Interrupt vector table
CA08
inttab:
CA08 C9C400F0    dfb   low smpint,high smpint,low board,high board
CA0C C8C400F0    dfb   low adcint,high adcint,low board,high board
CA10 CAC400F0    dfb   low md2int,high md2int,low board,high board
CA14 CEC400F0    dfb   low md3int,high md3int,low board,high board
CA18 A0C200F0    dfb   low rtcint,high rtcint,low board,high board
CA1C 9FC200F0    dfb   low keyint,high keyint,low board,high board
CA20 D2C400F0    dfb   low md6int,high md6int,low board,high board
CA24 D6C400F0    dfb   low md7int,high md7int,low board,high board
;
; SCSI command descriptor blocks
CA28 0000000000urcdb: dfb   0,0,0,0,0,1  ;test unit ready, linked
CA2E 1103000000edcddb: dfb   11h,3,0,0,0,0  ;space to end of data
CA34 0A01000008wrcdb: dfb   0ah,1,0,0,8,0  ;write 8 blocks
CA3A 1000000001fmcdcb: dfb   10h,0,0,0,1,0  ;write 1 file mark
CA40 0100000000rwcdcb: dfb   1,0,0,0,0,0  ;rewind
;
; Gain table
CA46 0000000101gtab: dfb   0,0,0,1,1,1,1,1,1,1,1,1,1,1,1,2      ;0-15

```



```

CEE6 0DOA537461      dfb    cr,lf,"Start time:  $"
CEE7 2020202050      dfb    " Parameters (ch,si,bl): $"
CF13 0DOA53746F      dfb    cr,lf,"Stop time:   $"
CF24 0720204144msgpa: dfb    7," ADC power turned on"
CF3A 20202D2048      dfb    " - Hit any key when done.$"
CF55 072020476Fmsggn: dfb    7," Good night.",cr,lf,"$"
CF66 0720204869msgwu: dfb    7," Hi! I am awake.$"
CF79 0720205374msgaq: dfb    7," Start data acquisition",cr,lf,"$"
CF95 0720204461msgac: dfb    7," Data acquisition complete$"
CFB2 0720204F42msgrl: dfb    7," OBS released",cr,lf,"$"
CFC4 07204D6973msgmi: dfb    7," Misdirected interrupt$"
CFDC 0DOA074472msgpu: dfb    cr,lf,7,"Drive motor power on$"
CFF4 0DOA074472msglu: dfb    cr,lf,7,"Drive logic power on$"
D00C 0DOA074472msgpd: dfb    cr,lf,7,"Drive motor power off$"
D025 0DOA074472msgld: dfb    cr,lf,7,"Drive logic power off$"
D03E 0DOA07496Emsgit: dfb    cr,lf,7,"Initializing tape drives"
D059 0DOA074472msgds: dfb    cr,lf,7,"Drive selected$"
D06B 0DOA07536Bmsged: dfb    cr,lf,7,"Skipped to end of data$"
D085 0DOA074669msgfm: dfb    cr,lf,7,"File mark written$"
D09A 0DOA075265msgrw: dfb    cr,lf,7,"Rewinding$"
D0A7 0DOA075461msgto: dfb    cr,lf,7,"Tape write time out abort$"
D0C4 0DOA074E6Fmsgel: dfb    cr,lf,7,"No tape motor power$"
D0DB 0DOA074E6Fmsge2: dfb    cr,lf,7,"No tape logic power$"
D0F2 0DOA074D6Fmsge3: dfb    cr,lf,7,"Motor power left on$"
D109 0DOA074C6Fmsge4: dfb    cr,lf,7,"Logic power left on$"
D120 0DOA074472msg5: dfb    cr,lf,7,"Drive not selected$"
D136 0DOA074661msg6: dfb    cr,lf,7,"Failed to find end of data$"
D154 0DOA074E6Fmsg7: dfb    cr,lf,7,"No bus-free mode obtained$"
D171 0DOA075068msg8: dfb    cr,lf,7,"Phase mismatch $"
D184 0DOA074461msg9: dfb    cr,lf,7,"Data write unsucessful$"
D19E 0DOA07454Fmsgel0: dfb    cr,lf,7,"EOF write unsucessful$"
D1B7 0DOA074661msgell: dfb    cr,lf,7,"Failed to rewind$"

;
; ***** Reset Bootstrap *****
;

DFF0          org    0dff0h
DFF0 EA04C000F0reset: jmpf  init,board
0000          end

```

Appendix E. Shot Table (Recording Schedule) Format

Format

- Line 1: OBS number, two digits
 Line 2: Release time in month, day, hour and minute, each of two digits and separated by a space
 Line 3: Wake-up time in the same format as above
 Line 4: Recording start time in the same format as above
 Line 5: Recording parameters (number of channels, sampling interval in ms*, and number of blocks) separated by commas
 Line 6: Recording stop time in the same format as above
 Lines 7ff: Repeat lines 3-6 for additional shot groups
 Last line: \$
-

*The actual sampling interval is slightly different from exact milliseconds in most cases. Appendix F gives the formula to calculate the true sampling intervals with some examples.

Example

05	— OBS No. 5
07 01 23 45	— releases on July 1 at 23h:45m
06 30 11 56	— wakes up on June 30 at 11h:56m
06 30 12 00	— recording starts on June 30 at 12h:00m
3,8,64	— 3 channels, 8 ms sampling interval, 64 blocks
06 30 14 00	— recording ends on June 30 at 14h:00m
06 30 23 54	— wakes up again on June 30 at 23h:54m
07 01 00 00	— recording starts on July 1 at 00h:00m
4,1,128	— 4 channels, 1 ms sampling interval, 128 blocks
07 01 12 00	— recording ends on July 1 at 12h:00m
\$	— end of shot table

Appendix F. Sampling Intervals

Sampling intervals are derived by counting down the clock rate of the baud-rate generator, and thus are slightly different from exact milliseconds in most cases. The actual sampling interval, τ_a in ms, can be calculated from a nominal sampling interval, τ_n in ms, by

$$\tau_a = \text{Int}(153.6 \tau_n + 0.5)/153.6$$

Their values for τ_n = 1 to 25 ms are listed below:

τ_n , ms	τ_a , ms	Error
1	1.0026	0.260%
2	1.9987	-0.065%
3	3.0013	0.043%
4	3.9974	-0.065%
5	5.0000	0.000%
6	6.0026	0.043%
7	6.9987	-0.019%
8	8.0013	0.016%
9	8.9974	-0.029%
10	10.0000	0.000%
11	11.0026	0.024%
12	11.9987	-0.011%
13	13.0013	0.010%
14	13.9974	-0.019%
15	15.0000	0.000%
16	16.0026	0.016%
17	16.9987	-0.008%
18	18.0013	0.007%
19	18.9974	-0.014%
20	20.0000	0.000%
21	21.0026	0.012%
22	21.9987	-0.006%
23	23.0013	0.006%
24	23.9974	-0.011%
25	25.0000	0.000%

Appendix G. Header and Data Formats

Header Format

Header occupies the first 16 bytes of each 4K block.

<u>Byte</u>	<u>Data</u>
0	Record number, low byte
1	Record number, high byte
2	Block number
3	Number of blocks in this record
4	Number of channels
5	Sampling interval in ms
6	Not used
7	Not used
8	OBS number
9	Year
10	Month
11	Day
12	Hour
13	Minute
14	Second
15	1/10 second

All header entries are in binary.

Data Format

Data occupies the remaining 4080 bytes of each block.
 Two bytes (16 bits) per data sample, multiplexed (i.e., channel 1, ch. 2, ..., ch. 1, ch. 2, ...).

<u>Byte</u>	<u>Bits</u>	<u>Data</u>
1st	6 msb	6 lsb of ADC output
1st	2 lsb	Exponent of power 5
2nd	all	8 msb of ADC output

ADC output is in offset binary with 2000h for zero input. To obtain amplitude referred to the highest gain, subtract 2000h from ADC and multiply by 5 raised to the power of the exponent.

Temporary Irregularity

For an unknown reason, the recorded data are shifted forward one byte, with the header for the first block starting at the second byte of the block and the last data byte of the block appearing at the first byte of the second block, and so on, with the very last byte of the last block missing.